



清華大學
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Beyond the Theoretical Limits of Language Modeling: A Distributional Perspective

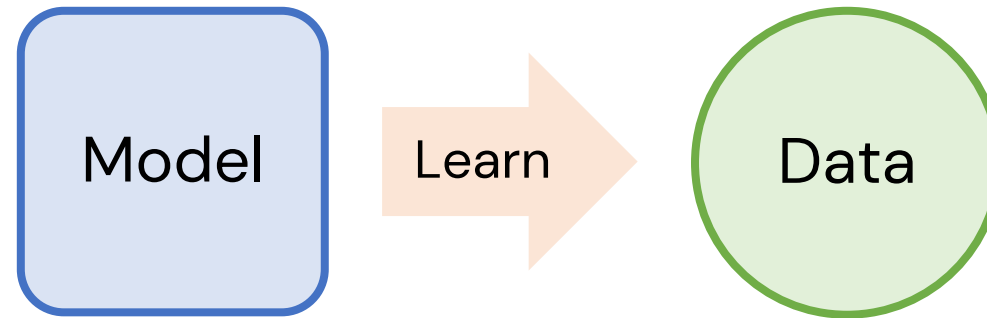
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Introduction



- Components of language modeling:



- ◆ **Language data:** $\mathcal{D} = \{\mathbf{x}^{(i)}\}_{i=1}^N$ drawn from data distribution
- ◆ **Probabilistic Model:** $p_{\theta}(\mathbf{x})$ map data point to probability
- ◆ **Learning objective:** $\mathcal{L}(\theta, \mathcal{D})$ learn model distribution from data
- Choice of model and objective seems not important nowadays. **Really?**

Introduction



- Modern recipe of language modeling:

Model: Neural language model

- Auto-Regressive (AR) model of sequence probability

$$p_{\theta}(\mathbf{x}) = \prod_{t=1}^T p_{\theta}(x_t | x_1, \dots, x_{<t})$$

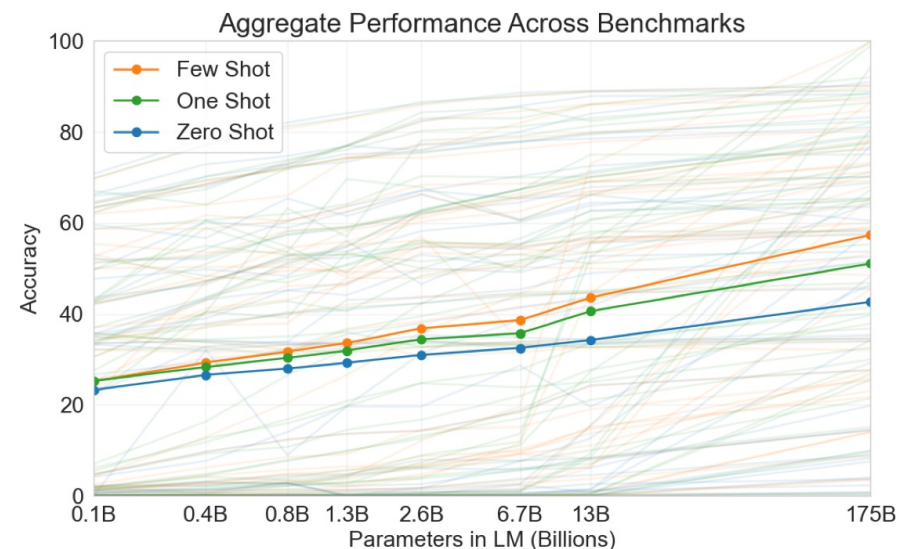
Auto-Regressive Modeling

Objective: Next token prediction

- Maximize the likelihood of samples in the dataset

$$\mathcal{L}_{\text{MLE}}(\theta; \mathcal{D}) = \underbrace{\mathbb{E}_{\mathbf{x} \sim \mathcal{D}} \left[-\log p_{\theta}(\mathbf{x}) \right]}_{\text{Maximum Likelihood Estimation}}$$

- Language modeling is shown to be the ultimate task towards “intelligence”

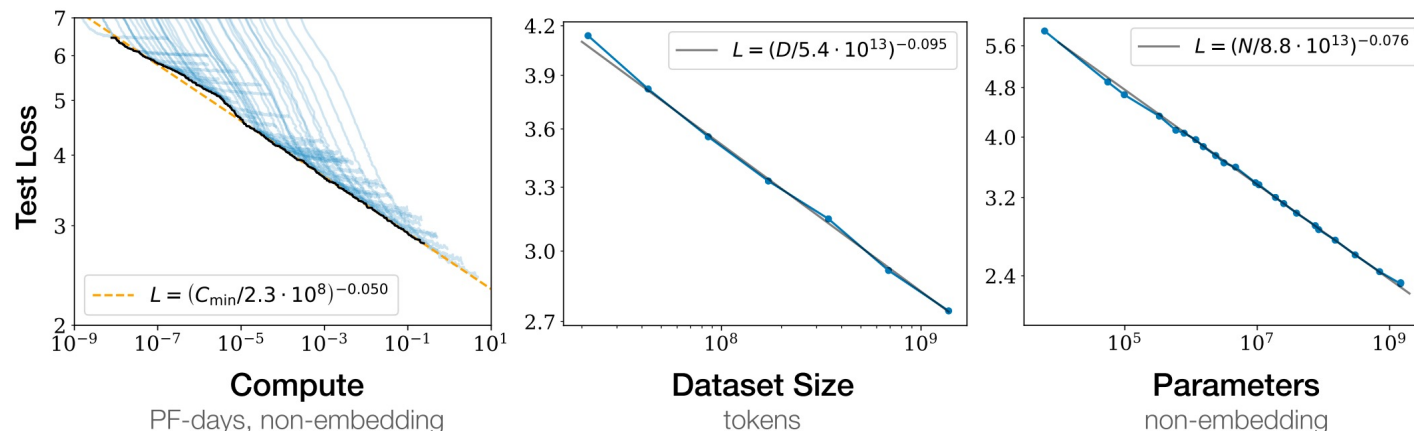


Averaged performance across tasks scales with model sizes

Introduction



- Empirical law for scaling AR language model (LMs) on the MLE loss



$$L(X) \propto X^{\alpha_X}$$

X is one factor from $\{C, D, N\}$

MLE loss has a **power-law** relationship with C, D, N

- ◆ The power law of scaling one factor depends on the **unbounded value** of the other two factors.
- ◆ The return becomes diminished when we **run out of the available human text data** or **cannot afford to increase the model size!**

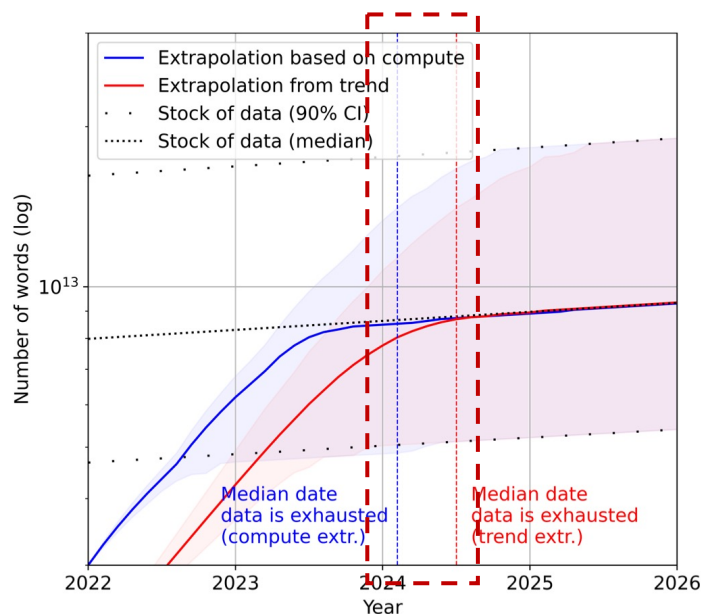
Introduction



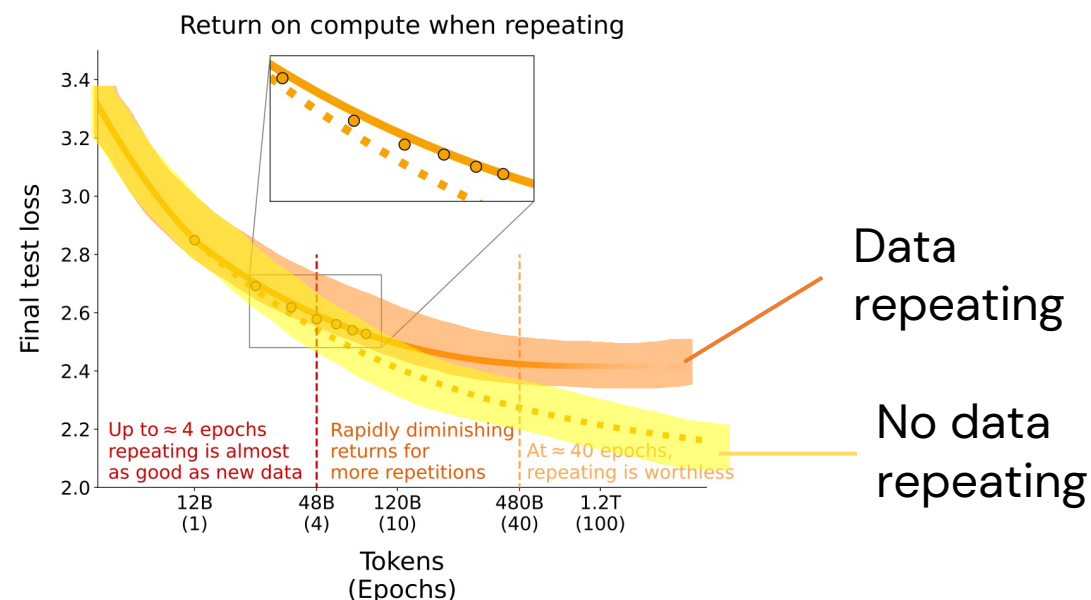
#1 What will happen when we run out of the available human text data?

- ◆ Llama3 was trained on 15T tokens, roughly the scale of the quality filtered subsets of Common Crawl, i.e., the high-quality English texts on the Internet.

Data will be “ran out” around 2024 (estimated in 2022)



language data on web



Data-Constrained Scaling law

Muennighoff, Niklas, et al. "Scaling Data-Constrained Language Models." *NeurIPS* (2024).

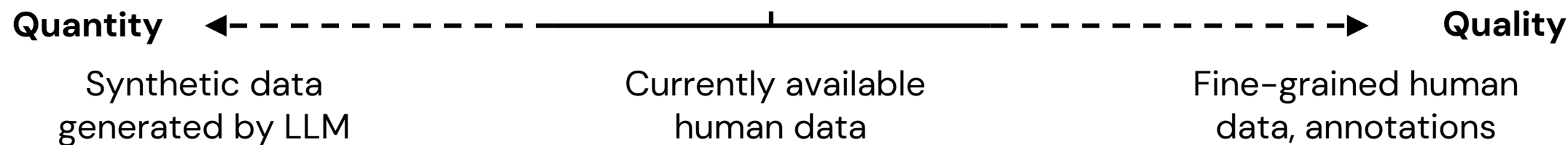
Villalobos, Pablo, et al. "Will we run out of data? an analysis of the limits of scaling datasets in machine learning." *arXiv preprint* (2022).

Introduction



#1 What will happen when we run out of the available human text data?

◆ The data spectrum

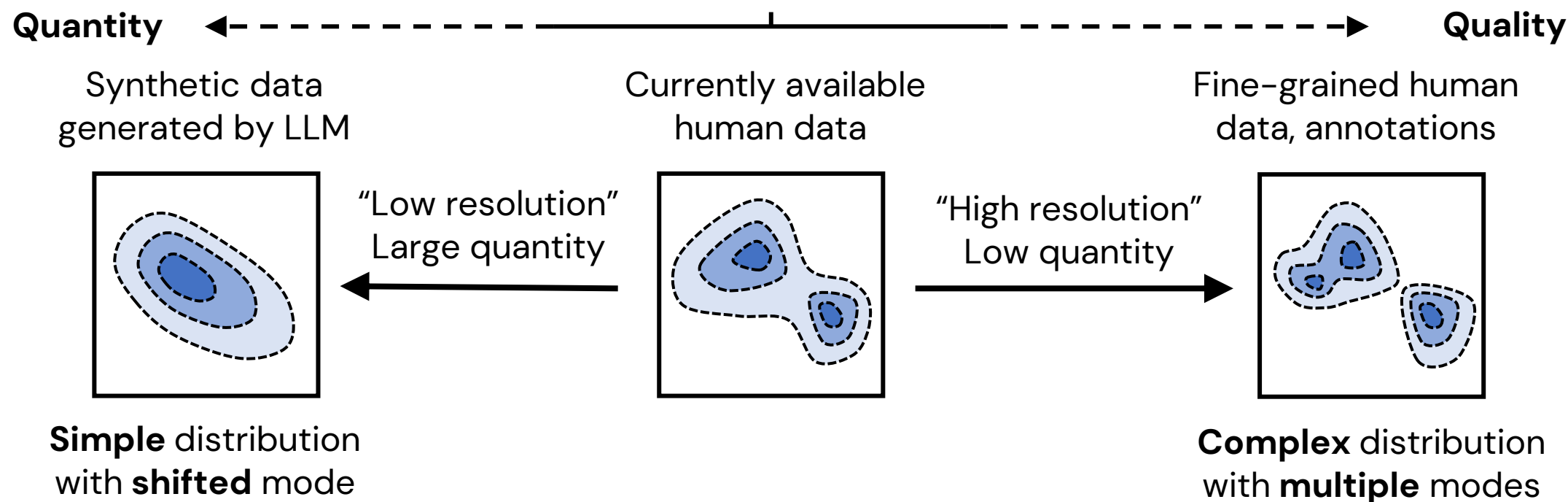


Introduction



#1 What will happen when we run out of the available human text data?

- ◆ The data spectrum from a **distributional** perspective

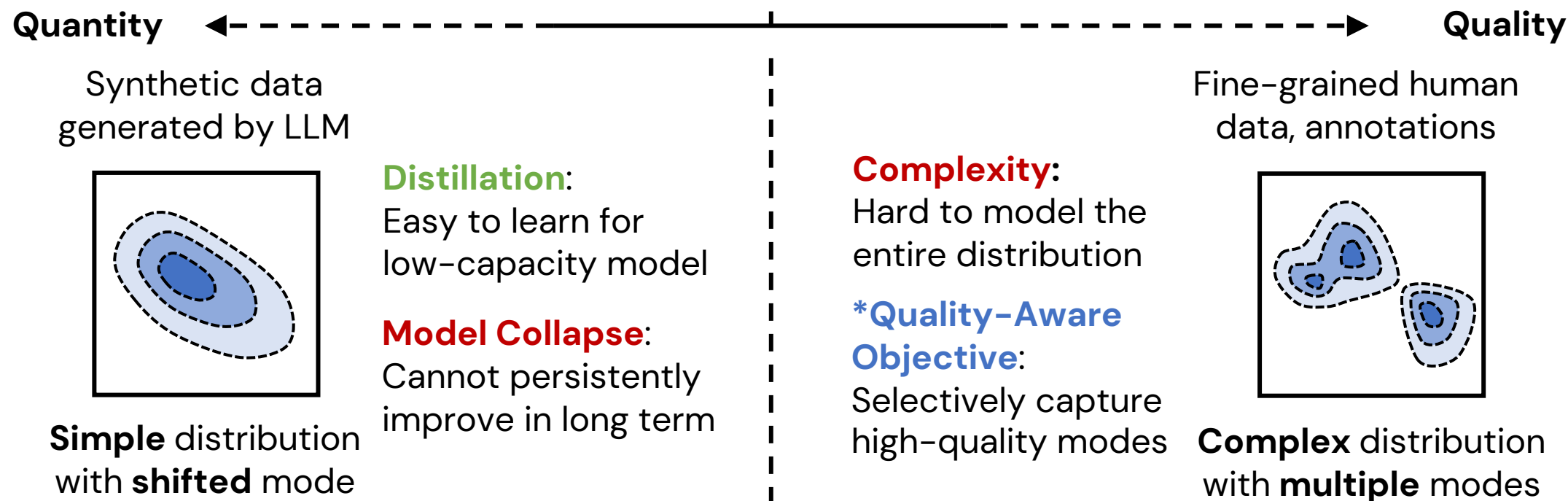


Introduction



#1 What will happen when we run out of the available human text data?

- ◆ The data spectrum from a **distributional** perspective



- ◆ MLE is **not** aware of quality but coverage (likelihood)!

#2 What is the parameter complexity of AR LMs to fit the growing data?

- ◆ **Theory (Informal):** AR LMs must be **large enough** to **efficiently compute** the probability of **arbitrary** sequence of length up to n under the complexity assumption of $\mathbf{P \neq NP}$.
- ◆ **Large parameter:**

$$|\theta_n^{\text{AR}}| = O(\text{Superpoly}(n))$$

- ◆ **Efficient computation:**

$$p_{\theta_n}(\mathbf{x}) = \prod_{t=1}^n p_{\theta_n}(x_t | x_1, \dots, x_{t-1})$$

$$p_{\theta_n}(x_t | \mathbf{x}_{<t}) = \frac{\sum_{\mathbf{x}'_{>t}} p_{\theta_n}(\mathbf{x}_{\leq t}, \mathbf{x}'_{>t})}{\sum_{\mathbf{x}'_{\geq t}} p_{\theta_n}(\mathbf{x}_{<t}, \mathbf{x}'_{\geq t})}$$

Assumption by AR:

Efficiently predict the **present** based on the **past** in time $O(\text{poly}(n))$

The **present** is predicted by marginalizing out **all possible futures** (Bayesian view)

#2 What is the parameter complexity of AR LMs to fit the growing data?

- ◆ **Theory (Informal):** AR LMs must be **large enough** to **efficiently compute** the probability of **arbitrary** sequence of length up to n under the complexity assumption of **P≠NP**.

- ◆ **Large parameter (space):**

$$|\theta_n^{\text{AR}}| = O(\text{Superpoly}(n))$$

- ◆ **Efficient computation (time):**

$$p_{\theta_n}(\mathbf{x}) = \prod_{t=1}^n p_{\theta_n}(x_t | x_1, \dots, x_{t-1})$$

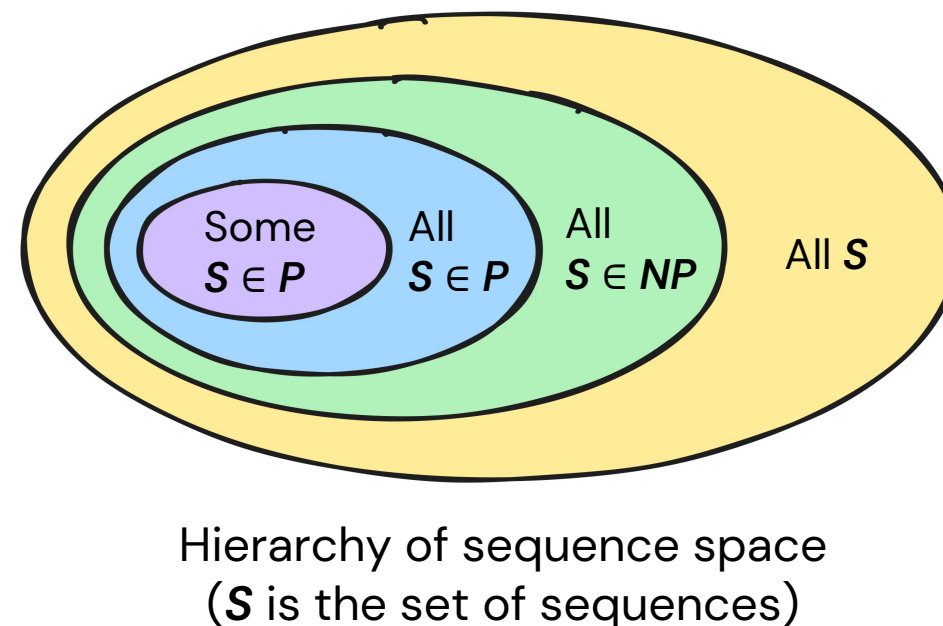
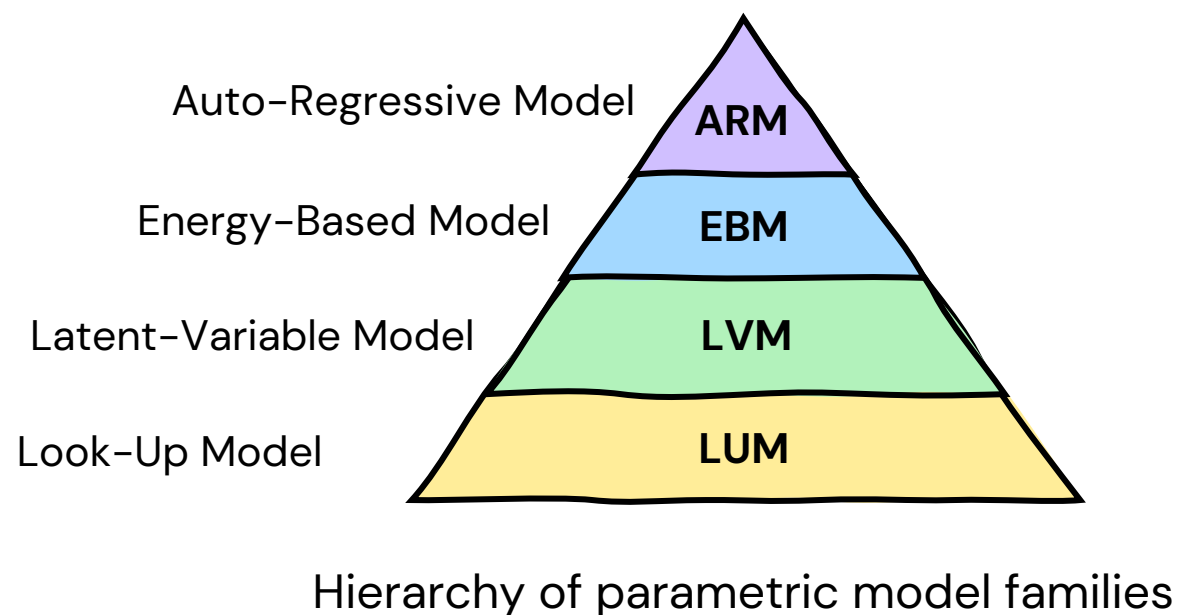
Assumption by AR:

Efficiently predict the **present** based on the **past** in time $O(\text{poly}(n))$

- ◆ **Intuition (Space-Time Tradeoff):** To accurately compute the probability of any sequence, the AR LM must have either **exponential-size computation** or **exponential-size parameters**.

#2 What is the parameter complexity of AR LMs to fit the growing data?

- ◆ **Corollary:** AR LMs with **compact parameters** grow as $O(\text{poly}(n))$ can only efficiently compute the probability of a **limited subset** of sequences of length up to n .
- ◆ Exist more **complex sequence spaces** captured by more **expressive model families**.



Beyond the theoretical limits of language modeling



- ◎ **Beyond MLE:** Quality-aware objective
 - ◆ **Reverse KL [ICML' 24]:** quality assessed by reward that captures human preference
 - ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory
- ◎ **Beyond AR:** Expressive model family
 - ◆ **Energy-based model [ICLR' 24]:** Augment AR model with a residual energy model
 - ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
 - ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up



◎ **Beyond MLE: Quality-aware objective**

- ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
- ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory

◎ **Beyond AR: Expressive model family**

- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
- ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
- ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up

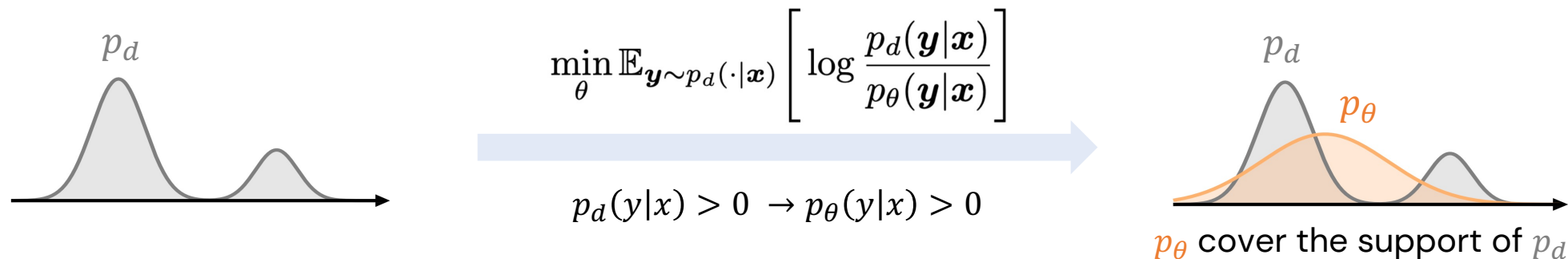
Learning as divergence minimization from a distributional perspective

- ◆ MLE minimizes the **forward-KL (FKL) divergence** from model dist. p_θ to data dist. p_d

$$\mathbb{E}_{p_d(\mathbf{y}|\mathbf{x})} \left[-\log p_\theta(\mathbf{y}|\mathbf{x}) \right] = \underbrace{\mathbb{D}_{\text{KL}}(p_d||p_\theta)[\mathbf{x}]}_{\text{forward KL}} + \underbrace{H(p_d)[\mathbf{x}]}_{\text{entropy}}$$

- ◆ Minimize FKL under **model misspecification**:

- p_d comes from a more expressive distribution family than p_θ
- **Example:** p_d is a mixture of Gaussians, p_θ is a single Gaussian



MLE for AR LM



○ Is MLE a universal objective for LM training?

◆ Pre-training stage:

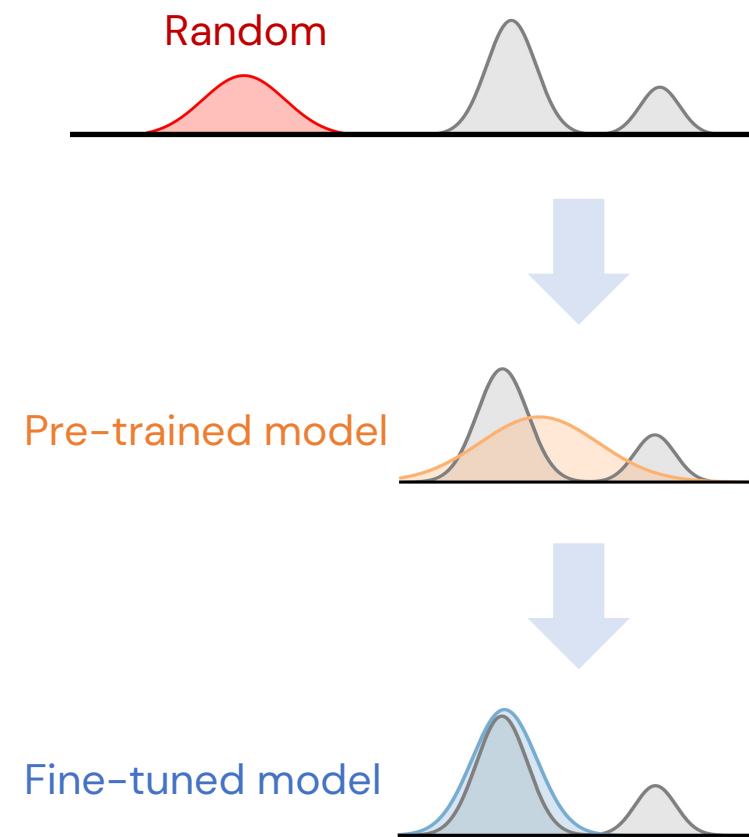
- Initialization: Random
- Data: large amount, diverse while noisy
- Goal: Learn basic knowledge (**coverage**)

◆ Fine-tuning stage:

- Initialization: Pre-trained model
- Data: limited amount, high-quality
- Goal: Learn fine-grained ability (**quality**)

○ MLE is not desirable when:

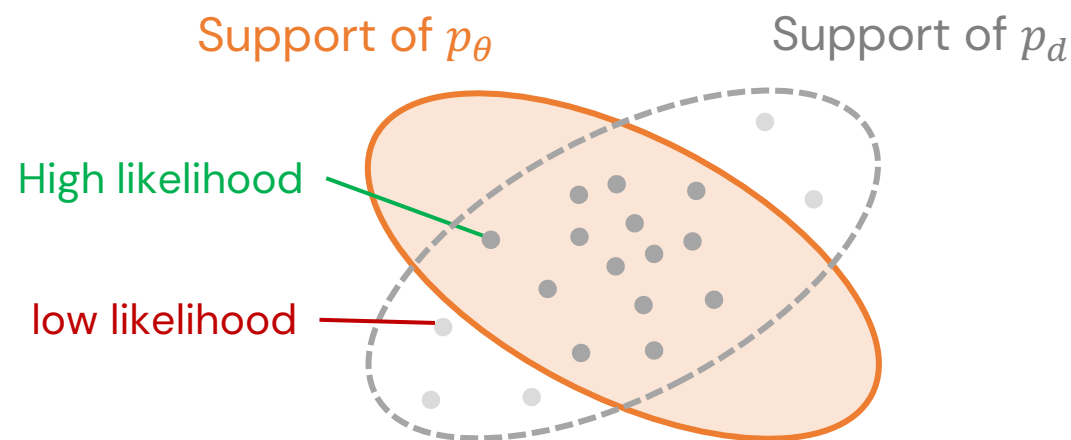
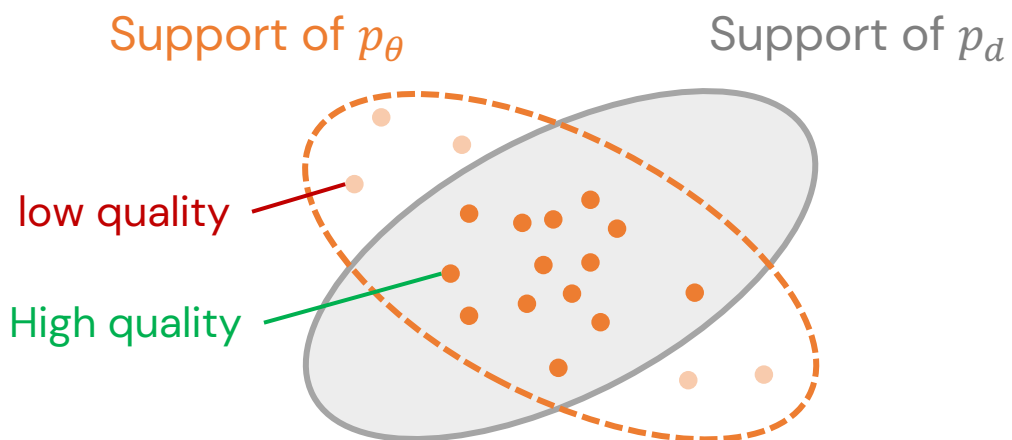
- ◆ Evaluation focuses on quality not coverage
- ◆ Model is mis-specified for the data distribution



Beyond MLE for AR LM



- Forward KL is not informative about the behavior of model on **quality**
- quality vs coverage
 - Quality: Evaluate **samples** generated by model
 - Coverage (likelihood): Evaluate model's **scores** on data samples



- Challenge of quality-aware objective:** Samples are hard to evaluate than scores!

Beyond the theoretical limits of language modeling



◎ Beyond MLE: Quality-aware objective

- ◆ **Reverse KL [1]**: quality assessed by reward that captures human preference
- ◆ Total variation distance [2]: quality assessed by the “optimal classifier” in theory

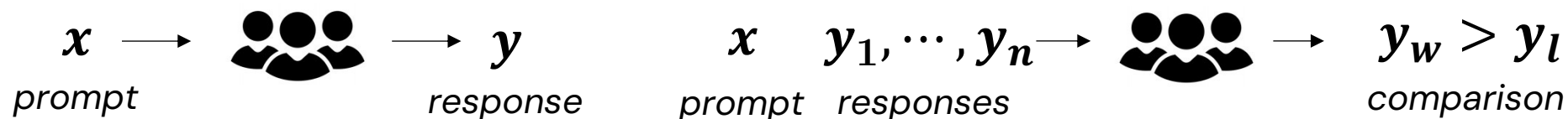
◎ Beyond AR: Expressive model family

- ◆ Energy-based model [3]: Augment AR model with a residual energy model
- ◆ Latent-variable model [4]: Condition AR model with a latent plan
- ◆ Look-up model [5]: Extend AR model with a parallel database look-up

Beyond MLE for AR LM



- Controlled assessment of quality by additional human annotation



Generative annotation

$$p_d(\mathbf{y}|\mathbf{x})$$



$$p_\theta(\mathbf{y}|\mathbf{x})$$

Generative model

Preferential annotation

$$p_d(\mathbf{y}_w \succeq \mathbf{y}_l | \mathbf{x})$$



$$r_\phi(\mathbf{x}, \mathbf{y})$$

Reward model



- Preference data: Fine-grained signal of **quality** to shape the target distribution
- Discrimination vs Generation: EBM can capture more complex distribution than ARM

- LM alignment with human preference [Ouyang et al., 2022]:

- Alignment objective (RLHF): KL-regularized reward maximization

$$\mathcal{J}_{\text{lhf}}^{\beta}(\pi_{\theta}) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \left(\underbrace{\mathbb{E}_{\pi_{\theta}(\mathbf{y}|\mathbf{x})} [r_{\phi}(\mathbf{x}, \mathbf{y})]}_{\substack{\text{Reward model} \\ (\text{proxy human preference})}} - \beta \underbrace{\mathbb{D}_{\text{KL}}[\pi_{\theta}(\mathbf{y}|\mathbf{x}) \parallel \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})]}_{\substack{\text{reference LM} \\ (\text{initialized by MLE})}} \right)$$
$$R(\mathbf{x}, \mathbf{y}) = r_{\phi}(\mathbf{x}, \mathbf{y}) - \beta \log \frac{\pi_{\theta}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})}$$

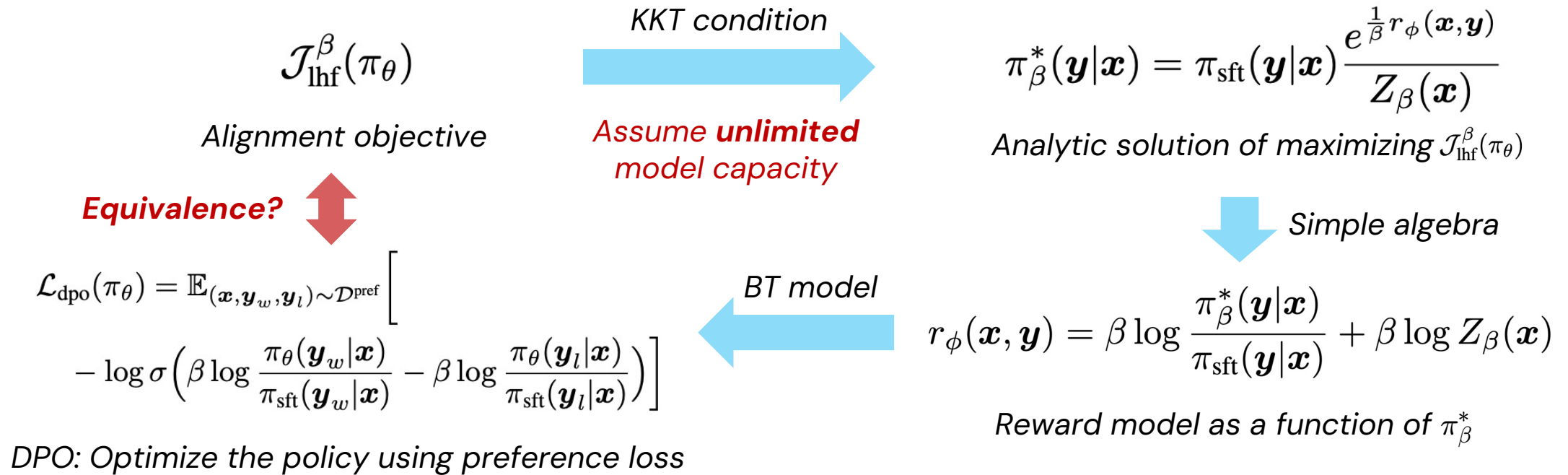
$$\nabla_{\theta} \mathcal{J}_{\text{lhf}}^{\beta}(\pi_{\theta}) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}, \mathbf{y} \sim \pi_{\theta}(\mathbf{y}|\mathbf{x})} \left[R(\mathbf{x}, \mathbf{y}) \nabla_{\theta} \log \pi_{\theta}(\mathbf{y}|\mathbf{x}) \right]$$

Policy gradient, Actor-Critic, e.g., PPO [Schulman et al., 2017]

RL has **high variance** in policy gradient estimation
RL needs to **sample in training loop** } **Inefficiency of convergence**

◉ Direct Preference Optimization (DPO) [Rafailov et al., 2023]:

◆ **Key intuition:** Policy optimization as reward modeling.



◆ \mathcal{L}_{dpo} is **not** equivalent to \mathcal{J}_{hf} considering the expressivity gap between π_θ and π_β^*

◉ What does the solution of RLHF look like under this practical constraint?

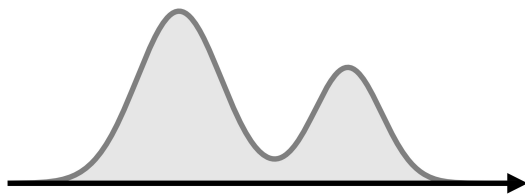
◆ KL-regularized RL as probability matching [Korbak et al., 2021].

$$\mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \left(\mathbb{E}_{\pi_{\theta}(\mathbf{y}|\mathbf{x})} [r_{\phi}(\mathbf{x}, \mathbf{y})] - \beta \mathbb{D}_{\text{KL}}[\pi_{\theta}(\mathbf{y}|\mathbf{x}) \parallel \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})] \right) \xleftrightarrow{\text{equivalent}} \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \left[\mathbb{D}_{\text{KL}}(\pi_{\theta}(\mathbf{y}|\mathbf{x}) \parallel \pi_{\beta_r}^*(\mathbf{y}|\mathbf{x})) \right]$$

Maximize reward with KL penalty
Minimize reverse KL divergence

◆ The asymmetry of KL divergence:

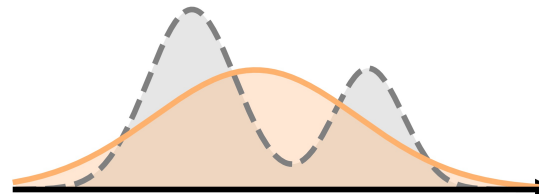
- Estimate the density of p



Target distribution $p(x)$

Forward KL

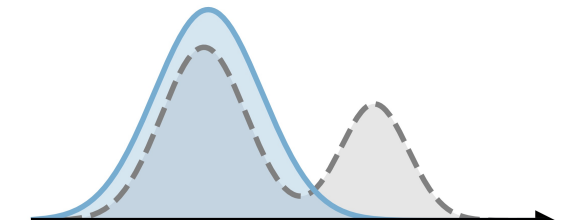
$$\mathbb{D}_{\text{KL}}(p \parallel \hat{p}) = \mathbb{E}_{x \sim p} \left[\log \frac{p(x)}{\hat{p}(x)} \right]$$



Mean-seeking solution

Reverse KL

$$\mathbb{D}_{\text{KL}}(\hat{p} \parallel p) = \mathbb{E}_{x \sim \hat{p}} \left[\log \frac{\hat{p}(x)}{p(x)} \right]$$



Mode-seeking solution

Reverse KL for LM Alignment



- Policy optimization as probability matching under Reverse KL [Ji et al., 2023] (ICML' 24):

- Without loss of generality, consider the generalized alignment objective:

$$\mathcal{J}_{\text{hf}}^{\beta_r}(\pi_{\theta}^{\beta_{\pi}}) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \left(\mathbb{E}_{\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x})} [r_{\phi}(\mathbf{x}, \mathbf{y})] - \beta_r \mathbb{D}_{\text{KL}}[\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x}) \parallel \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})] \right)$$

- $\pi_{\theta}^{\beta_{\pi}}$ is the geometric mean of π_{θ} and π_{sft}

$$\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x}) \propto \pi_{\theta}(\mathbf{y}|\mathbf{x})^{\beta_{\pi}} \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})^{1-\beta_{\pi}}$$

- Decompose the KL regularization

$$\beta = \underbrace{\beta_r}_{\text{regularize reward}} \cdot \underbrace{\beta_{\pi}}_{\text{regularize policy}}$$

- Analytic solution is also π_{β}^* .

- Unify the regularization setting of PPO ($\beta_{\pi} = 1, \beta_r = \beta$) and DPO ($\beta_{\pi} = \beta, \beta_r = 1$)

Reverse KL for LM Alignment



- Deriving the probability matching objective of $\mathcal{J}_{\text{lhf}}^{\beta_r}(\pi_{\theta}^{\beta_{\pi}})$

$$\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x})} \left[\log \frac{\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x})}{\pi_{\beta_r}^*(\mathbf{y}|\mathbf{x})} \right]$$



Importance Sampling (IS)
 π_{sft} as the proposal distribution

$$\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[\frac{\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \log \frac{\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x})}{\pi_{\beta_r}^*(\mathbf{y}|\mathbf{x})} \right]$$



Define $f_{\theta}(\mathbf{x}, \mathbf{y}) = \log \pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x}) - \log \pi_{\text{sft}}(\mathbf{y}|\mathbf{x})$
as the log policy ratio

$$\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[e^{f_{\theta}(\mathbf{x}, \mathbf{y})} \log \frac{e^{f_{\theta}(\mathbf{x}, \mathbf{y})}}{\frac{1}{Z_{\beta_r}(\mathbf{x})} e^{\frac{r_{\phi}(\mathbf{x}, \mathbf{y})}{\beta_r}}} \right]$$

Reverse KL for LM Alignment



- Deriving the probability matching objective of $\mathcal{J}_{\text{lhf}}^{\beta_r}(\pi_{\theta}^{\beta_{\pi}})$

$$\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[e^{f_{\theta}(\mathbf{x}, \mathbf{y})} \log \frac{e^{f_{\theta}(\mathbf{x}, \mathbf{y})}}{\frac{1}{Z_{\beta_r}(\mathbf{x})} e^{\frac{r_{\phi}(\mathbf{x}, \mathbf{y})}{\beta_r}}} \right]$$

- The partition function $Z_{\beta_r}(\mathbf{x})$ is intractable.
- Inspiration from Self-Normalized Importance Sampling (SNIS)
- Sample K i.i.d. continuations $\mathbf{y}_{1:K} = \{\mathbf{y}_1, \dots, \mathbf{y}_K\}$ from $\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})$

$$Z_{\beta_r}(\mathbf{x}) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} [\exp(\frac{r_{\phi}(\mathbf{x}, \mathbf{y})}{\beta_r})]$$

$$\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}} \parallel \pi_{\beta_r}^*) = \lim_{K \rightarrow \infty} \sum_{k=1}^K \frac{e^{f_{\theta}(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K e^{f_{\theta}(\mathbf{x}, \mathbf{y}_j)}} \log \frac{\frac{e^{f_{\theta}(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K e^{f_{\theta}(\mathbf{x}, \mathbf{y}_j)}}}{\frac{e^{\frac{1}{\beta_r} r_{\phi}(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K \frac{1}{\beta_r} e^{r_{\phi}(\mathbf{x}, \mathbf{y}_j)}}$$

Distribution of log policy ratio

Distribution of reward model

Reverse KL for LM Alignment



- Deriving the probability matching objective of $\mathcal{J}_{\text{lhf}}^{\beta_r}(\pi_{\theta}^{\beta_{\pi}})$

$$\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}} \parallel \pi_{\beta_r}^*) = \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})} \left[e^{f_{\theta}(\mathbf{x}, \mathbf{y})} \log \frac{e^{f_{\theta}(\mathbf{x}, \mathbf{y})}}{\frac{1}{Z_{\beta_r}(\mathbf{x})} e^{\frac{r_{\phi}(\mathbf{x}, \mathbf{y})}{\beta_r}}} \right]$$

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$$\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}} \parallel \pi_{\beta_r}^*) = \lim_{K \rightarrow \infty} \sum_{k=1}^K \frac{e^{f_{\theta}(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K e^{f_{\theta}(\mathbf{x}, \mathbf{y}_j)}} \log \frac{\frac{e^{f_{\theta}(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K e^{f_{\theta}(\mathbf{x}, \mathbf{y}_j)}}}{\frac{e^{\frac{1}{\beta_r} r_{\phi}(\mathbf{x}, \mathbf{y}_k)}}{\sum_{j=1}^K \frac{1}{\beta_r} e^{r_{\phi}(\mathbf{x}, \mathbf{y}_j)}}}$$

Reverse KL $\mathbb{D}_{\text{KL}}(p_{f_{\theta}} \parallel p_{r_{\phi}})$ of $p_{f_{\theta}}$ and $p_{r_{\phi}}$

Reverse KL for LM Alignment



Efficient Exact Optimization (**EXO**) of the alignment objective

Learning from the reward model

$$\mathcal{L}_{\text{exo}}(\pi_\theta) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}_{1:K} | \mathbf{x})} \left[\mathbb{D}_{\text{KL}}(p_{f_\theta}(\cdot | \mathbf{y}_{1:K}, \mathbf{x}) \| p_{r_\phi}(\cdot | \mathbf{y}_{1:K}, \mathbf{x})) \right]$$

- Where we define: *regularize policy*

$$p_{f_\theta}(i | \mathbf{y}_{1:K}, \mathbf{x}) = \frac{e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_i | \mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_i | \mathbf{x})}}}{\sum_{j=1}^K e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_j | \mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_j | \mathbf{x})}}}$$

regularize reward

$$p_{r_\phi}(i | \mathbf{y}_{1:K}, \mathbf{x}) = \frac{e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_i)}}{\sum_{j=1}^K e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_j)}}$$

Learning from the preference data ($K=2$)

$$\mathcal{L}_{\text{exo-pref}}(\pi_\theta) = \mathbb{E}_{(\mathbf{x}, \mathbf{y}_w, \mathbf{y}_l) \sim \mathcal{D}^{\text{pref}}} \left[\mathbb{D}_{\text{KL}}(p_{f_\theta}(\cdot | \mathbf{y}_w, \mathbf{y}_l, \mathbf{x}) \| p_{r_h}(\cdot | \mathbf{y}_w, \mathbf{y}_l, \mathbf{x})) \right]$$

- Where the preference probability $p_{r_h}(\cdot | \mathbf{y}_w, \mathbf{y}_l, \mathbf{x})$ is a label-smoothed one-hot distribution.

Reverse KL for LM Alignment



Analysis

- ◆ Unbiased gradient ($K \rightarrow \infty$):

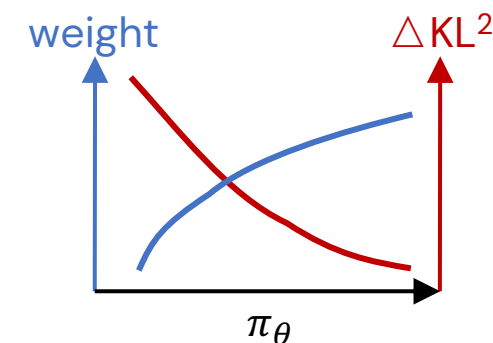
$$\begin{aligned}\nabla_{\theta} \mathcal{L}_{\text{exo}}(\pi_{\theta}) &= \nabla_{\theta} \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} [\mathbb{D}_{\text{KL}}(\pi_{\theta}^{\beta_{\pi}}(\mathbf{y}|\mathbf{x}) || \pi_{\beta_r}^*(\mathbf{y}|\mathbf{x}))] \\ &= -\frac{1}{\beta_r} \nabla_{\theta} \mathcal{J}_{\text{lhf}}^{\beta_r}(\pi_{\theta}^{\beta_{\pi}}).\end{aligned}$$

- In practice, a finite K slightly introduces bias while reduces variance.

- ◆ Asymptotic variance comparison:

$$\text{Var}[\hat{\text{KL}}_{\text{exo}}] = \mathbb{E}_{\mathbf{y} \sim \pi_{\theta}} \left[\frac{w(\mathbf{x}, \mathbf{y})}{\mathbb{E}_{\mathbf{y}' \sim \pi_{\theta}} [w(\mathbf{x}, \mathbf{y}')] } \left(\log \frac{\pi_{\theta}(\mathbf{y}|\mathbf{x})}{\pi_{\beta}^*(\mathbf{y}|\mathbf{x})} - \text{KL} \right)^2 \right] \quad w(\mathbf{x}, \mathbf{y}) = \frac{\pi_{\theta}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})}$$

$$\text{Var}[\hat{\text{KL}}_{\text{ppo}}] = \mathbb{E}_{\mathbf{y} \sim \pi_{\theta}} \left[\left(\log \frac{\pi_{\theta}(\mathbf{y}_i|\mathbf{x})}{\pi_{\beta}^*(\mathbf{y}_i|\mathbf{x})} - \text{KL} \right)^2 \right]$$



approx. negative correlation

Comparison with DPO



Generalizing DPO:

- ◆ Sample K completions $\mathbf{y}_{1:K} = \{\mathbf{y}_1, \dots, \mathbf{y}_K\}$ from $\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})$
- ◆ Generalize hard label to soft label

$$\mathcal{L}_{\text{dpo-rw}}(\pi_\theta) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} \mathbb{E}_{\pi_{\text{sft}}(\mathbf{y}_{1:K}|\mathbf{x})} \left[- \sum_{i=1}^K \frac{e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_i)}}{\sum_{j=1}^K e^{\frac{1}{\beta_r} r_\phi(\mathbf{x}, \mathbf{y}_j)}} \log \frac{e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_i|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_i|\mathbf{x})}}}{\sum_{j=1}^K e^{\beta_\pi \log \frac{\pi_\theta(\mathbf{y}_j|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}_j|\mathbf{x})}}} \right]$$

Forward KL $\mathbb{D}_{\text{KL}}(p_{f_\theta} || p_{r_\phi})$ of p_{f_θ} and p_{r_ϕ} (up to a constant)

- ◆ The gradient of DPO-rw aligns with the gradient of the forward KL asymptotically for policy with **arbitrary** θ when $K \rightarrow \infty$.

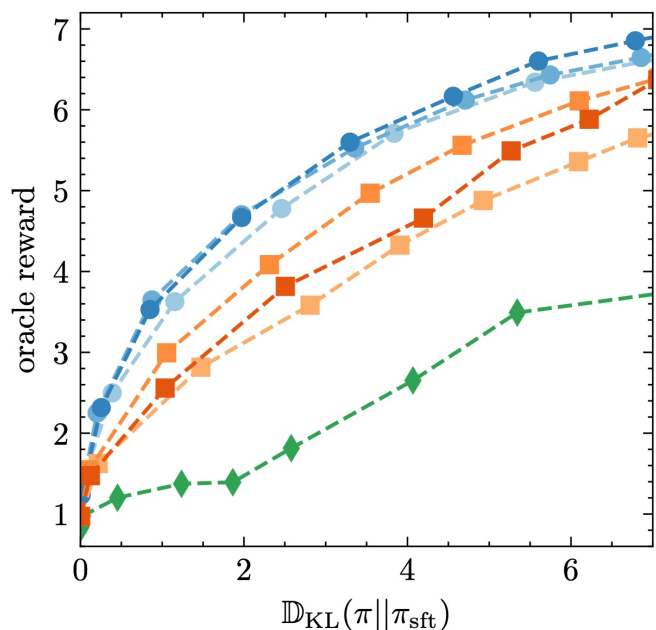
$$\nabla_\theta \mathcal{L}_{\text{dpo-rw}}(\pi_\theta) = \nabla_\theta \mathbb{E}_{\mathbf{x} \sim \mathcal{D}^{\text{pref}}} [\mathbb{D}_{\text{KL}}(\pi_{\beta_r}^*(\mathbf{y}|\mathbf{x}) || \pi_\theta^{\beta_\pi}(\mathbf{y}|\mathbf{x}))]$$

- **Inexactness:** DPO minimizes the forward KL, while RLHF, e.g., PPO minimizes the reverse KL.

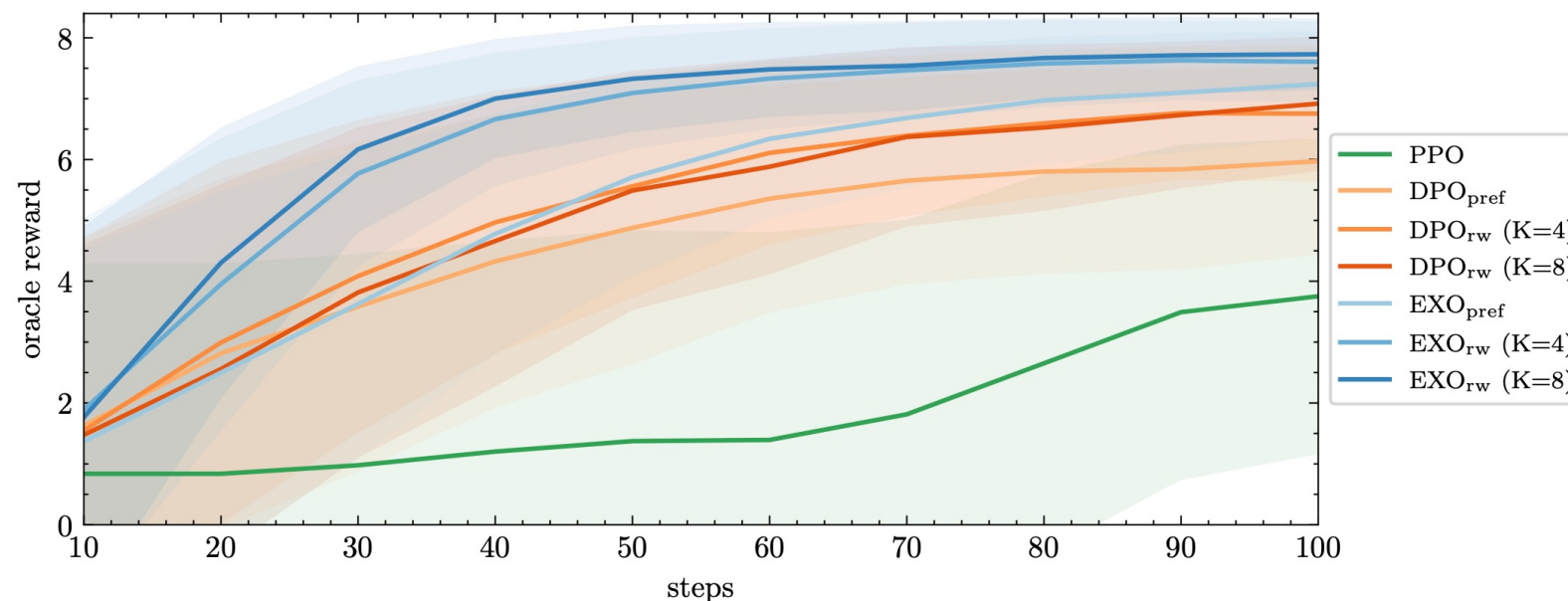
Experiments



- Synthetic experiment: Generate IMDB review with positive sentiment
 - ◆ Oracle reward (Human labeler): Classifier trained on IMDB review classification dataset



Oracle reward vs KL



Oracle reward vs Training steps

Experiments

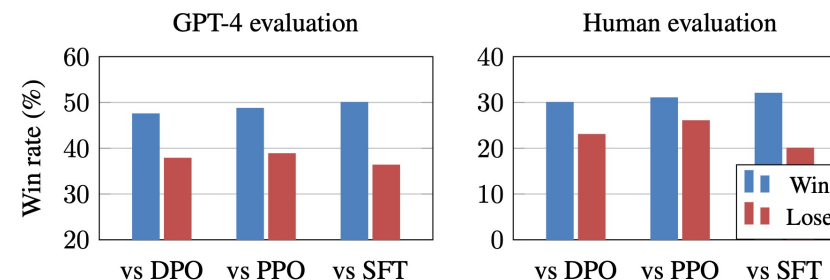


- Alignment on real human preferences:

- ◆ Text summarization: TL;DR preference dataset
- ◆ Dialogue generation: Anthropic-HH dataset (helpfulness subset)
- ◆ Instruction following: Filtered real user query from an online API

Method	Reward Model (%)		GPT-4 (%)	
	vs SFT	vs Chosen	vs SFT	vs Chosen
w/ Preferences				
DPO _{pref}	68.3	23.7	57.0	30.5
EXO_{pref}	92.5	60.1	83.0	55.0
w/ Reward Model				
Best-of- <i>N</i>	99.3	75.8	83.5	60.0
PPO	93.2	58.3	77.0	52.0
DPO _{rw}	82.7	39.8	70.0	41.0
EXO_{rw}	97.3	76.4	88.5	64.0

Method	Reward Model (%)		GPT-4 (%)	
	vs SFT	vs Chosen	vs SFT	vs Chosen
w/ Preferences				
DPO _{pref}	66.3	65.1	58.0	37.0
EXO_{pref}	76.4	76.7	73.0	51.0
w/ Reward Model				
Best-of- <i>N</i>	94.6	98.2	86.0	63.0
PPO	75.0	74.0	66.5	52.0
DPO _{rw}	79.9	81.3	75.5	49.0
EXO_{rw}	85.6	87.2	83.5	60.0



- ◆ Outperforms DPO and PPO in both settings of learning from preferences & reward model.
- ◆ On par with Best-of-*N* (*N*=128) but much more computationally efficient in inference.
- ◆ Scaling to realistic instruction-following dataset with consistent improvement.

Experiments

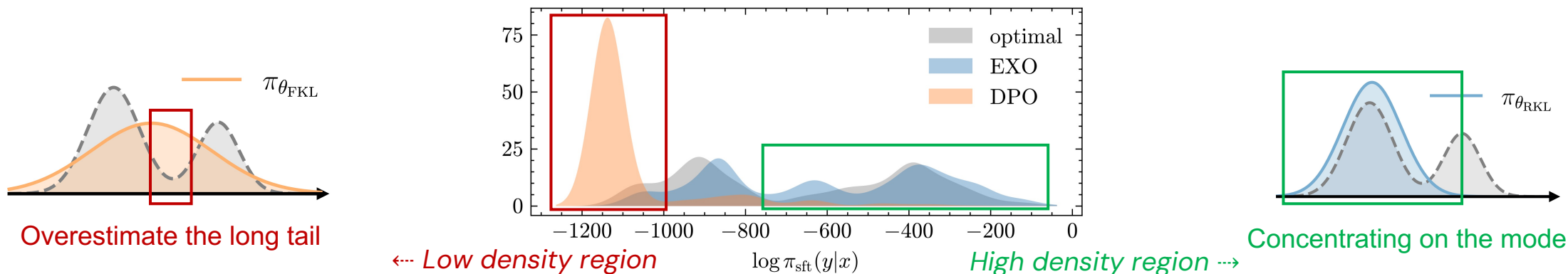


Visualization: Compare the density of DPO and EXO with the optimal policy

- Given a test prompt **"This Fox spectacle was a big hit when released in "**
- Estimate the empirical policy distribution of π_θ and π_β^* by SNIS:

$$\hat{\pi}_\theta(\mathbf{y}_i|\mathbf{x}) = \frac{M\pi_\theta(\mathbf{y}_i|\mathbf{x})}{\sum_{j=1}^M \pi_\theta(\mathbf{y}_j|\mathbf{x})/\pi_{\text{sft}}(\mathbf{y}_j|\mathbf{x})} \quad \hat{\pi}_\beta^*(\mathbf{y}_i|\mathbf{x}) = \frac{M\pi_{\text{sft}}(\mathbf{y}_i|\mathbf{x}) \exp(r(\mathbf{x}, \mathbf{y}_i)/\beta)}{\sum_{j=1}^M \exp(r(\mathbf{x}, \mathbf{y}_j)/\beta)}$$

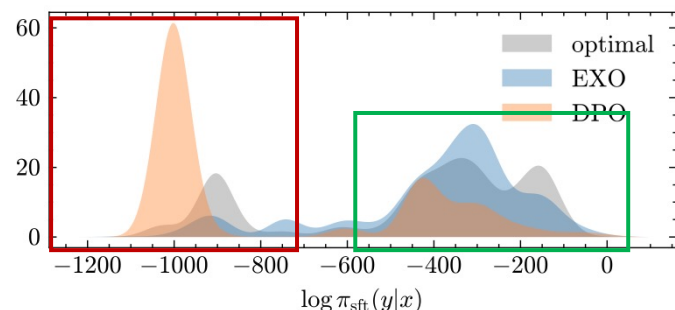
- Use Kernel Density Estimation to estimate the density and plot the ratio $\rho_{\hat{\pi}}(\mathbf{y}|\mathbf{x}) = \frac{\hat{\pi}(\mathbf{y}|\mathbf{x})}{\pi_{\text{sft}}(\mathbf{y}|\mathbf{x})}$



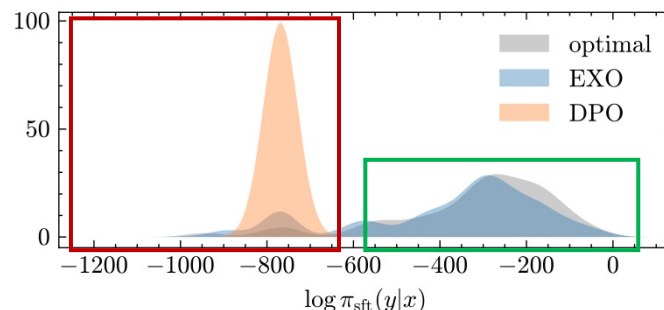
Experiments



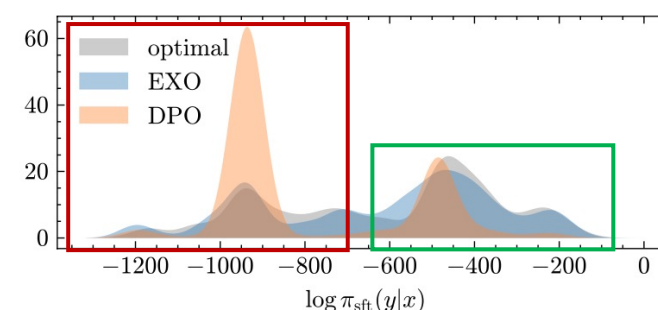
More visualization cases: (prevailing phenomenon, no cherry-picking)



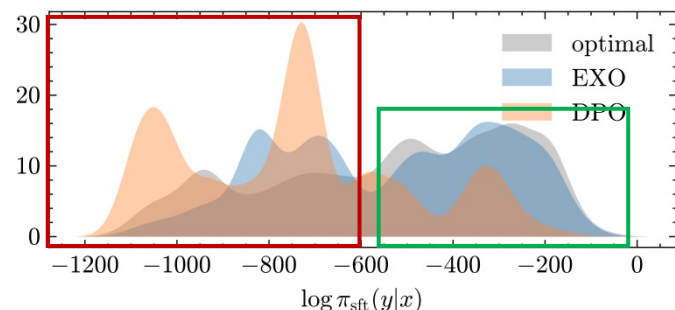
Estimated density ratio of the EXO, DPO and optimal policy given the prompt "Is this supposed to be serious? I hope not".



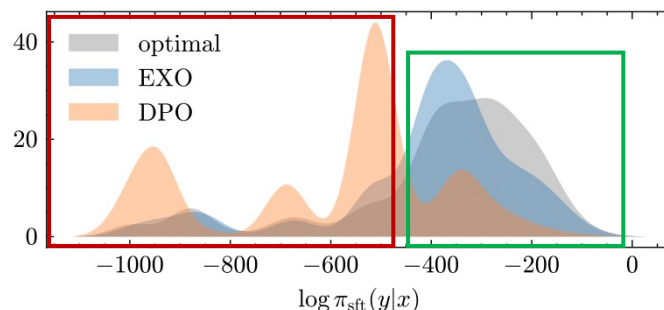
Estimated density ratio of the EXO, DPO and optimal policy given the prompt "Great book, great movie, great soundtrack. Frank".



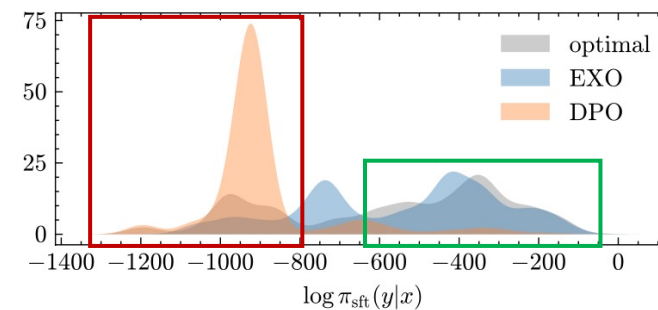
Estimated density ratio of the EXO, DPO and optimal policy given the prompt "What we have here the standard Disney direct to DVD".



Estimated density ratio of the EXO, DPO and optimal policy given the prompt "This is indeed the film that popularized kung".



Estimated density ratio of the EXO, DPO and optimal policy given the prompt "This movie is about a group of people who are".



Estimated density ratio of the EXO, DPO and optimal policy given the prompt "Once the slow beginning gets underway, the film kicks".

Beyond the theoretical limits of language modeling



◎ **Beyond MLE: Quality-aware objective**

- ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
- ◆ **Total variation distance [ICLR' 23]:** quality assessed by the “optimal classifier” in theory

◎ **Beyond AR: Expressive model family**

- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
- ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
- ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up

- Total variation distance (TVD): quality assessed by “**optimal classifier**”
 - ◆ TVD reflects the “accuracy” of an optimal classifier that try to discriminate true data and model generated data

$$c \sim p(c) = \text{Bernoulli}\left(\frac{1}{2}\right) \quad \text{Prior label distribution}$$

$$\mathbf{y} \sim p(\mathbf{y}|\mathbf{x}, c) = \begin{cases} p_d(\mathbf{y}|\mathbf{x}) & \text{if } c = 1 \quad \text{True data} \\ p_\theta(\mathbf{y}|\mathbf{x}) & \text{if } c = 0 \quad \text{Model generated data} \end{cases}$$

$$\|p_d - p_\theta\|_{\text{TV}} = 1 - 2 \underbrace{\inf_f \mathbb{P}\left(f(\mathbf{x}, \mathbf{y}) \neq c\right)}_{\text{error rate}} \quad \text{TVD defined by optimal error rate}$$

- ◆ **Intuition:** The closer p_θ and p_d is, the harder for the optimal classifier to discriminate.
(The upper-bound of error rate is 50%, i.e., by chance)

TVD for LM Fine-Tuning



Learning objective for LM based on TVD [Ji et al., 2023] (ICLR'23 Oral):

Measuring the distance in discrete sequence space:

$$\begin{aligned}\|p_d - p_\theta\|_{\text{TV}} &= \frac{1}{2} \sum_{\mathbf{y} \in \mathcal{Y}} |p_d(\mathbf{y}|\mathbf{x}) - p_\theta(\mathbf{y}|\mathbf{x})| && \text{L1-distance} \\ &= 1 - \sum_{\mathbf{y} \in \mathcal{Y}} \min(p_d(\mathbf{y}|\mathbf{x}), p_\theta(\mathbf{y}|\mathbf{x}))\end{aligned}$$

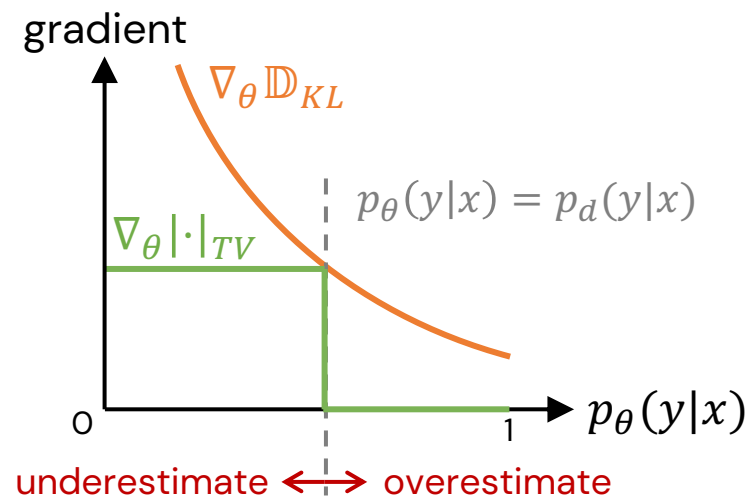
Gradient analysis: $y \sim p_d$

Gradient of FKL

$$\nabla_\theta \mathbb{D}_{\text{KL}}(p_d \| p_\theta) \approx -\frac{\nabla_\theta p_\theta(\mathbf{y}|\mathbf{x})}{p_\theta(\mathbf{y}|\mathbf{x})} \quad \text{Assign non-zero } p_\theta \text{ to every data point}$$

Gradient of TVD

$$\nabla_\theta \|p_d - p_\theta\|_{\text{TV}} \approx \begin{cases} -\frac{\nabla_\theta p_\theta(\mathbf{y}|\mathbf{x})}{p_d(\mathbf{y}|\mathbf{x})}, & p_\theta(\mathbf{y}|\mathbf{x}) < p_d(\mathbf{y}|\mathbf{x}) \\ 0, & p_\theta(\mathbf{y}|\mathbf{x}) \geq p_d(\mathbf{y}|\mathbf{x}) \end{cases}$$



TVD for LM Fine-Tuning



Learning objective for LM based on TVD [Ji et al., 2023] (ICLR'23 Oral):

Measuring the distance in discrete sequence space:

$$\begin{aligned}\|p_d - p_\theta\|_{\text{TV}} &= \frac{1}{2} \sum_{\mathbf{y} \in \mathcal{Y}} |p_d(\mathbf{y}|\mathbf{x}) - p_\theta(\mathbf{y}|\mathbf{x})| && \text{L1-distance} \\ &= 1 - \sum_{\mathbf{y} \in \mathcal{Y}} \min(p_d(\mathbf{y}|\mathbf{x}), p_\theta(\mathbf{y}|\mathbf{x}))\end{aligned}$$

Gradient analysis: $y \sim p_d$

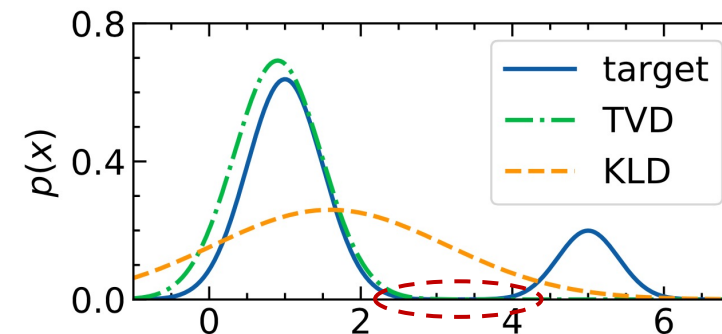
- Gradient of FKL

- Learning objective for LM based on TVD [Ji et al., 2023] (ICLR)
 - Measuring the distance in discrete sequence space:
 - Gradient analysis: $y \sim p_d$
 - Gradient of FKL
 - Gradient of TVD

Assign non-zero p_θ to every data point

- Gradient of TVD

$$\nabla_\theta \|p_d - p_\theta\|_{\text{TV}} \approx \begin{cases} -\frac{\nabla_\theta p_\theta(\mathbf{y}|\mathbf{x})}{p_d(\mathbf{y}|\mathbf{x})}, & p_\theta(\mathbf{y}|\mathbf{x}) < p_d(\mathbf{y}|\mathbf{x}) \\ 0, & p_\theta(\mathbf{y}|\mathbf{x}) \geq p_d(\mathbf{y}|\mathbf{x}) \end{cases}$$



overestimate "data void"

TVD for LM Fine-Tuning

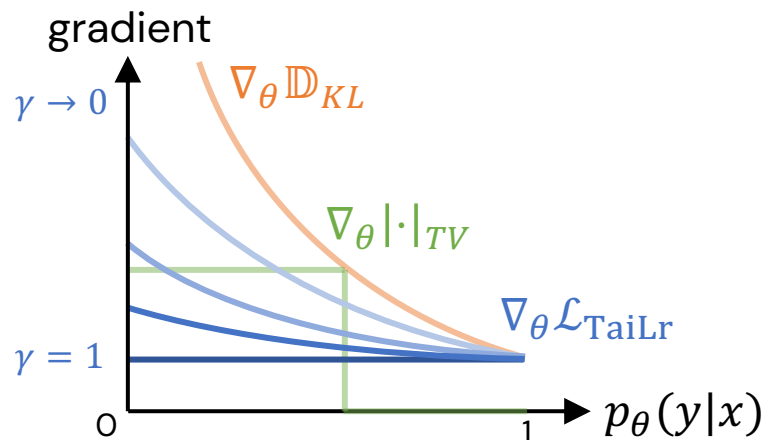


Learning objective for LM based on TVD [Ji et al., 2023] (ICLR'23 Oral):

◆ Tailr objective

$$\mathcal{L}_{\text{Tailr}}(w; \theta) = - \underbrace{\left(\frac{p_{\theta}^{\leq t}(w)}{\gamma + (1 - \gamma)p_{\theta}^{\leq t}(w)} \right)}_{\text{stop gradient}} \log p_{\theta}^{\leq t}(w)$$

◆ γ trade-offs bias and variance: $\gamma = 1$ (unbiased TVD) $\gamma \rightarrow 0$ (bias to KLD)



Experiments



Experiments: Various text generation tasks

Other MLE variants

TVD-based

Method	Dev BLEU	Test BLEU
MLE	35.81 [‡]	34.27 [‡]
Unlikelihood	33.92 [‡]	32.82 [‡]
D2GPo	36.09 [‡]	34.50 [‡]
Loss truncation	35.63 [†]	34.48 [‡]
GOLD	35.74 [‡]	34.68 [‡]
TaiLr	36.44	35.05

One-way Training	Test BLEU
BiBERT (Table 2, Xu et al. 2021)	37.58
BiBERT (Our implementation)	38.01
BiBERT + TaiLr	39.12
Dual-directional Training + Fine-Tuning	Test BLEU
BiBERT (Table 3, Xu et al. 2021)	38.61
BiBERT (Our implementation)	38.73
BiBERT + TaiLr	39.23

Machine translation: Improve over the **2022 SOTA (BiBERT)** on IWSLT14

Method	B-1 [↑]	D-4 [↑]	rep-8 [↓]	Mauve [↑]
MLE	27.85	84.28	10.31 [†]	56.42 [‡]
Unlikelihood	27.88	85.46	10.06	59.35 [‡]
D2GPo	22.73 [‡]	84.10	10.04	53.35 [‡]
Loss truncation	19.49 [‡]	76.51 [‡]	13.41 [‡]	45.35 [‡]
GOLD	25.25 [‡]	46.98 [‡]	28.23 [‡]	15.44 [‡]
TaiLr	28.62	85.56	9.73	64.64

Long text generation

Method	R-1	R-2	R-L
MLE	38.24 [‡]	19.12	35.70 [†]
Unlikelihood	37.80 [‡]	18.34 [‡]	34.84 [‡]
D2GPo	38.52 [†]	18.92 [†]	35.64 [‡]
Loss truncation	38.62	19.29	35.85 [†]
GOLD	38.57 [†]	19.27	35.79 [†]
TaiLr	38.82	19.50	36.24

Text summarization

Beyond MLE for AR LM



- ⦿ **Takeaway & Future:**
- ⦿ The desired learning goal should capture quality, which might not always has a tractable form.
- ⦿ Effectiveness and efficiency of learning: Bias–variance tradeoff
 - ◆ Variance: Sparsity and complexity of data
 - ◆ Bias: Inductive bias of estimation method
- ⦿ **Principle:** Reduce variance with controlled bias

Beyond the theoretical limits of language modeling



- ◎ **Beyond MLE: Quality-aware objective**
 - ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
 - ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory
- ◎ **Beyond AR: Expressive model family**
 - ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
 - ◆ Latent-variable model [EMNLP' 21]: Condition AR model with a latent plan
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Beyond the theoretical limits of language modeling



◎ Beyond MLE: Quality-aware objective

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- ◆ **Energy-based model [ICLR' 24]**: Augment AR model with a residual energy model
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Energy-Based Model



- Definition: Assign low energy to sequence with high probability

$$p(\mathbf{y}|\mathbf{x}) = \frac{e^{-E_{\theta}(\mathbf{x}, \mathbf{y})}}{\sum_{\mathbf{y}'} e^{-E_{\theta}(\mathbf{x}, \mathbf{y}')}} = \frac{e^{-E_{\theta}(\mathbf{x}, \mathbf{y})}}{Z(\mathbf{x})}$$

- Energy function: $E_{\theta}(\mathbf{x}, \mathbf{y})$ scores the complete sequence \mathbf{y}
 - Partition function: $Z(\mathbf{x})$ is the normalizing constant which is intractable
- Advantage: Conditional probability implicitly marginalizing out the future

$$p(y_t | \mathbf{y}_{<t}, \mathbf{x}) = \frac{\sum_{\mathbf{y}'_{>t}} e^{-E_{\theta}(\mathbf{x}, \mathbf{y}_{<t}, y_t, \mathbf{y}'_{>t})}}{\sum_{\mathbf{y}'_{\geq t}} e^{-E_{\theta}(\mathbf{x}, \mathbf{y}_{<t}, \mathbf{y}'_{\geq t})}} = \frac{Z(\mathbf{x}, \mathbf{y}_{<t}, y_t)}{Z(\mathbf{x}, \mathbf{y}_{<t})}$$

- Intuition: EBM shows that **exactly computing** the conditional probability requires considering **all possibilities** in the future. Local normalization is insufficient (AR model)

Energy-Based Model



- ⊙ **Disadvantage:** MLE, sampling for EBM is expensive due to intractable $Z(\mathbf{x})$
- ⊙ **Noise-Contrastive Estimation (NCE):** Sampling-free method
 - ◆ **Intuition:** Reducing energy **only** on correct data points does not guarantee increasing their probability. Need to “push them down wrong points”.

- ◆ Ranking objective:

$$\min_{\theta} \mathbb{E}_{\mathbf{y}_+ \sim p_d, \mathbf{y}_-^{(1:K)} \sim p_N} \left[-\log \frac{e^{s_{\theta}(\mathbf{x}, \mathbf{y}_+)}}{e^{s_{\theta}(\mathbf{x}, \mathbf{y}_+)} + \sum_{k=1}^K e^{s_{\theta}(\mathbf{x}, \mathbf{y}_-^{(k)})}} \right]$$

- ◆ Score function:

$$s_{\theta}(\mathbf{x}, \mathbf{y}) = -E_{\theta}(\mathbf{x}, \mathbf{y}) - \log p_N(\mathbf{y}|\mathbf{x})$$

- ◆ It is critical to choose an **appropriate noise distribution** which is useful for fine-grained characterization of the energy landscape.

- ◉ **Residual EBM:** Leverage the inductive bias of local normalized AR model

$$p(\mathbf{y}|\mathbf{x}) = p_{\theta}(\mathbf{y}|\mathbf{x}) \frac{\exp[-E_{\phi}(\mathbf{x}, \mathbf{y})]}{Z(\mathbf{x})}$$

- ◆ NCE improves over the base AR model by setting $p_N = p_{\theta}$

- ◆ **Facilitate sampling from EBM:**

(1) **Sampling** from AR proposal

$$\{\mathbf{y}^{(k)}\}_{k=1}^K \sim p_{\theta}(\mathbf{y}|\mathbf{x})$$

(2) **Resampling** with energy function

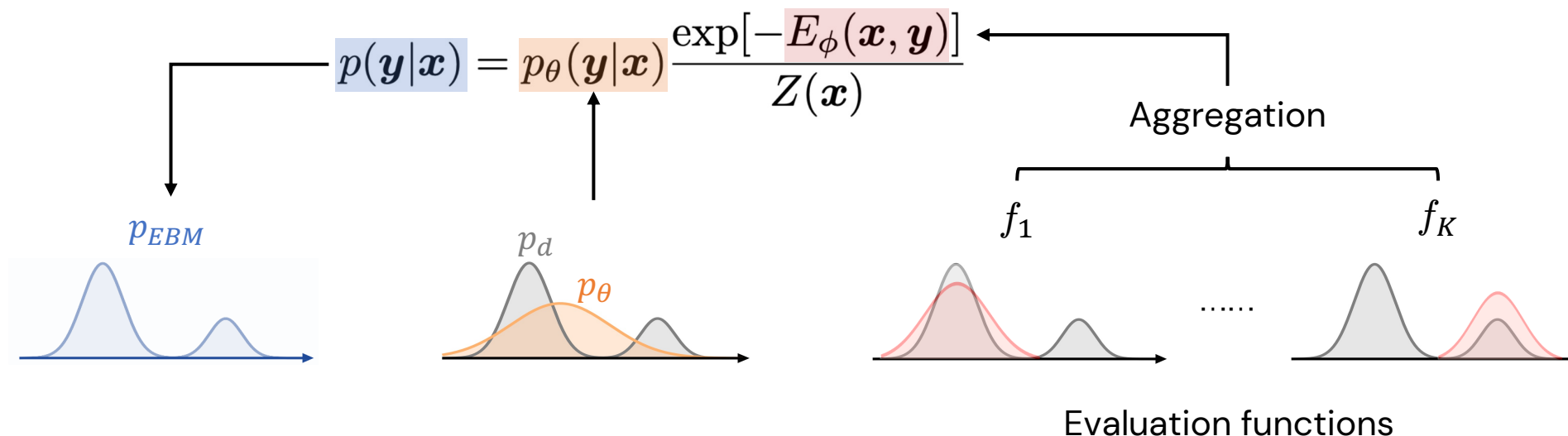
$$\mathbf{y} \sim \text{Cat}\left(\text{softmax}[-E_{\theta}(\mathbf{x}, \mathbf{y}^{(k)})]\right)$$

- ◆ Training a new EBM using NCE every time is **costly** and **restrictive**, considering a large number of available **evaluation metrics, reward model, classifiers**, etc.
- ◆ Can we leverage those evaluation functions to build EBM?

Energy-Based Model



- Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):



- ◆ $\{f_k\}_{k=1}^K$ evaluate different aspect of the distribution
- ◆ How to aggregate different evaluation functions?

Energy-Based Model



- Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):

- ◆ **Aggregation criteria for unconditional LM decoding:**

- **Overall quality:** Samples drawn from EBM are “good” on **all** evaluation functions

$$\mathbb{E}_{\mathbf{y} \sim p}[f_k(\mathbf{y})] = \mathbb{E}_{\mathbf{y} \sim p_d}[f_k(\mathbf{y})], \forall k \in [1, K]$$

- **Regularization:** Explore within the support of AR LM distribution:

$$\min_p \mathbb{D}_{\text{KL}}(p \| p_\theta)$$

- ◆ The optimal solution is exactly EBM:

$$p^*(\mathbf{y}) \propto p_\theta(\mathbf{y}) \exp \left[- \sum_{k=1}^K \mu_k^* f_k(\mathbf{y}) \right]$$

- Energy function is the **linear combination** of evaluation functions $\{f_k\}_{k=1}^K$
- K optimal weights $\{\mu_k^*\}_{k=1}^K$ are automatically determined by solving the constraints.

Energy-Based Model

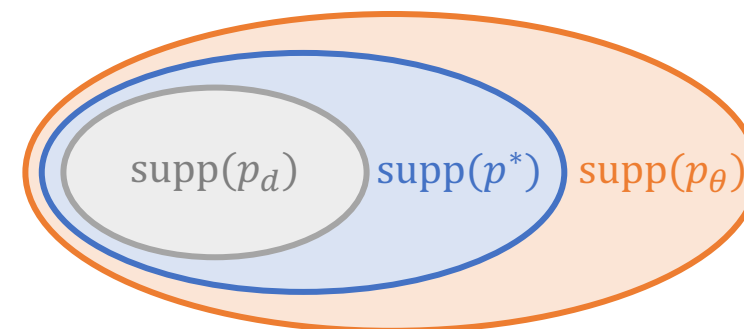


- Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):

- Theoretical results:** p^* is a better approximation of p_d

- #1** p^* close the **gap of support** to p_d

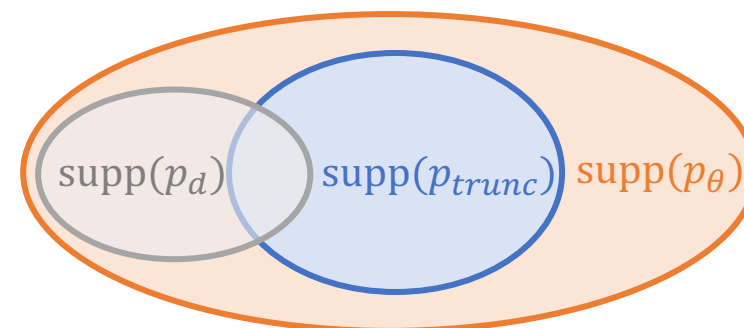
$$\text{supp}(p_d) \subseteq \text{supp}(p^*) \subseteq \text{supp}(p_\theta)$$



- Iterating the process effectively approaches p_d

- Heuristic decoding method, e.g., top-k/p truncates p_θ "too hard"**

$$\text{supp}(p_d) \not\subseteq \text{supp}(p_{\text{trunc}}) \subseteq \text{supp}(p_\theta)$$



- Lead to a biased distribution
- Lose coverage to the complete p_d

Energy-Based Model



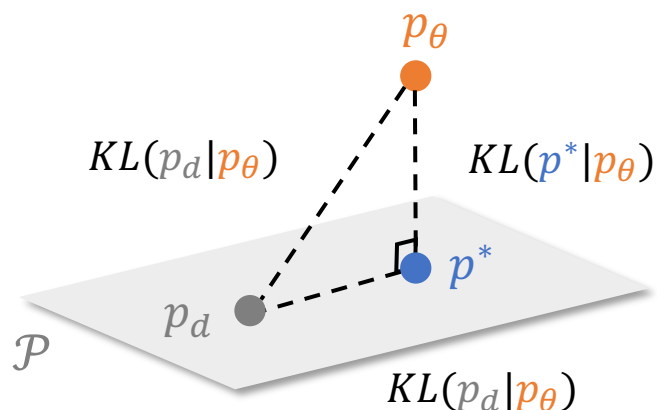
Build EBM by aggregating evaluation functions [Ji et al., 2024] (ICLR' 24):

◆ **Theoretical results:** p^* is a better approximation of p_d

#2 p^* is guaranteed to improve **perplexity** (2^H) on p_d

$$H(p_d, p^*) = H(p_d, p_\theta) - \underbrace{\mathbb{D}_{\text{KL}}(p^* || p_\theta)}_{\text{non-negative}}$$

• Pythagorean theorem of KL divergence:



p^* is the **projection** of p_θ on the hyperplane:

$$\mathcal{P} = \{p \mid \mathbb{E}_{\mathbf{y} \sim p}[f_k(\mathbf{y})] = \mathbb{E}_{\mathbf{y} \sim p_d}[f_k(\mathbf{y})], \forall k \in [1, K]\}$$

Experiments



Experiments: Unconditional LM decoding

◆ **Evaluation functions:** automatic metrics, e.g., coherence, repetition, diversity, etc.

Truncated Sampling

Contrastive Search

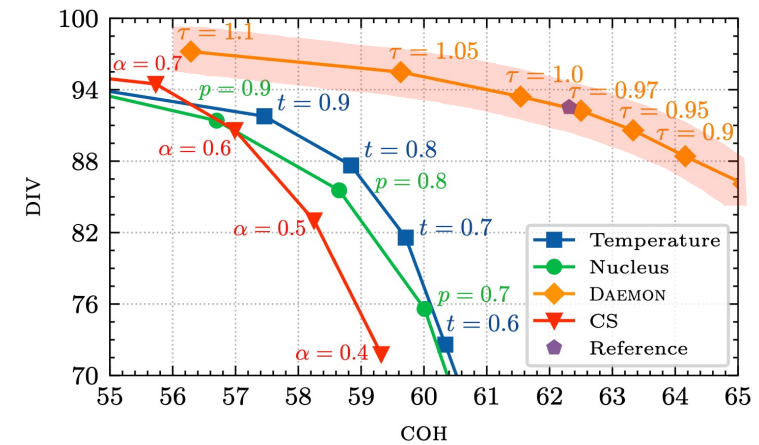
Sample from EBM

Method			Wikipedia		e^{ENT}	MAU	
	SR-4	TR-32	COH	DIV			
Reference	0.48	21.3	62.3	92.5	23.2	-	
GPT-2 XL	Greedy	60.9	65.5	60.2	8.03	2.29	59.7
	Top-k	2.11	23.4	60.9	87.8	10.1	77.8
	Nucleus	1.19	20.0	57.3	92.4	17.3	78.3
	Typical	0.81	17.4	54.9	94.5	30.1	78.7
	CD	1.31	28.2	68.7	85.9	7.55	77.8
	CS	1.78	23.0	56.9	90.6	5.25	83.3
	DAEMON	0.42	22.5	62.5	92.2	22.8	88.1
	Greedy	54.8	60.4	62.0	0.12	2.78	64.8
	Top-k	2.44	24.1	61.3	86.6	13.9	77.5
	Nucleus	2.33	21.9	59.1	88.6	18.9	80.1
OPT-6.7B	Typical	1.06	19.6	57.0	92.9	31.9	77.7
	CD	2.90	26.5	68.6	82.3	11.7	78.6
	CS	1.13	21.7	57.7	91.8	8.72	83.3
	DAEMON	0.38	21.6	62.3	92.6	22.7	90.7

Performance on various metrics

Model	Wikipedia		News	
	ori	imp	ori	imp
GPT-2 XL	23.1	22.0	13.9	13.1
OPT-6.7B	16.4	16.2	10.8	10.2

(Tuning-free) Perplexity improvement



coherence-diversity tradeoff

Experiments



Experiments: Multi-objective alignment

- ◆ **Evaluation functions:** reward models, e.g., helpfulness, harmless, etc.
- ◆ **Conditional EBM:**

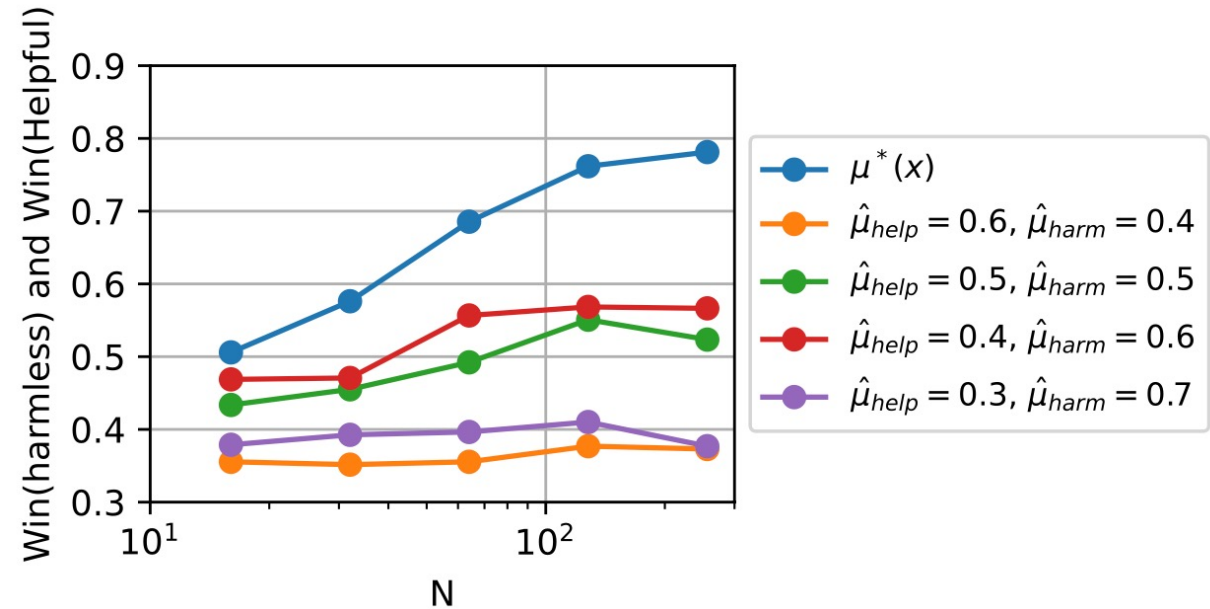
$$p^*(\mathbf{y}|\mathbf{x}) \propto p_\theta(\mathbf{y}|\mathbf{x}) \exp \left[- E(\mathbf{x}, \mathbf{y}) \right]$$

- **Optimal instance-level weight:**

$$E(\mathbf{x}, \mathbf{y}) = \sum_{k=1}^K \mu_k^*(\mathbf{x}) f_k(\mathbf{x}, \mathbf{y})$$

- **Empirical global weight:**

$$E(\mathbf{x}, \mathbf{y}) = \sum_{k=1}^K \hat{\mu}_k f_k(\mathbf{x}, \mathbf{y})$$



Best-of-N experiments on Anthropic-HH

Energy-Based Model



- ◎ **Takeaway & Future:**

- ◎ EBM Learning: reward modeling

- ◆ Aggregation: Compositionality of EBM
- ◆ Calibration: Uncertainty-Awareness

- ◎ EBM Inference: Acceleration

- ◆ Re-sampling / Rejection sampling
- ◆ MCMC method: Langevin Dynamics
- ◆ Score-guided sampling (learn a score function as in diffusion)
- ◆ Learn tractable AR sampler (lossy due to capacity gap between ARM and EBM)

Beyond the theoretical limits of language modeling



◎ Beyond MLE: Quality-aware objective

- ◆ Reverse KL [ICML' 24]: quality assessed by reward that captures human preference
- ◆ Total variation distance [ICLR' 23]: quality assessed by the “optimal classifier” in theory

◎ Beyond AR: Expressive model family

- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
- ◆ **Latent-variable model [EMNLP' 21]**: Condition AR model with a latent plan
- ◆ Look-up model [EMNLP' 20]: Extend AR model with a parallel database look-up

Latent-Variable Model



- ◉ **Advantage:** Model the unobserved as latent variable increases capacity

$$p(\mathbf{y}|\mathbf{x}) = \int p_{\theta}(\mathbf{y}|\mathbf{x}, \mathbf{z})p_{\theta}(\mathbf{z}|\mathbf{x})d\mathbf{z}$$

- ◆ Theorem [Lin et al., 2020]: Latent-variable AR model has support $\mathcal{S} \in NP$
- ◆ Intuition: Marginalizing over the **latent “compression”** \mathbf{z} of the future output \mathbf{y}
- ◉ **Disadvantage:** No tractable exact inference of likelihood due to integral over \mathbf{z} !
- ◉ **Variational inference:**

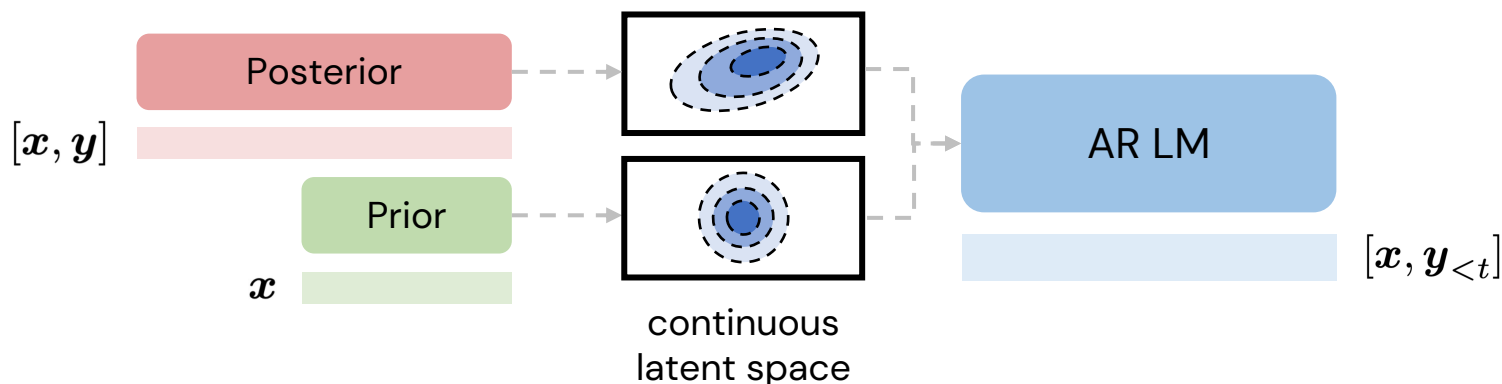
$$p(\mathbf{y}|\mathbf{x}) = \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y})} \left[\frac{p_{\theta}(\mathbf{y}|\mathbf{x}, \mathbf{z})p_{\theta}(\mathbf{z}|\mathbf{x})}{q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y})} \right]$$

- ◆ The inference is “amortized” by first finding a **good approximated posterior** q_{ϕ} which later facilitates inferring \mathbf{y} from \mathbf{z} .

Latent-Variable Model



- AR model with continuous latent variable [Bowman et al., 2015]:



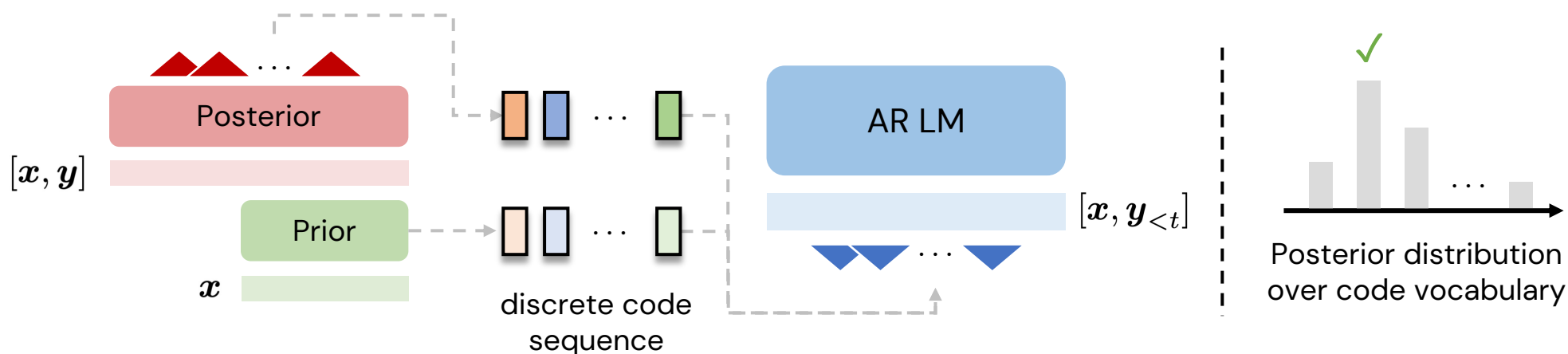
$$\underbrace{-\log p(\mathbf{y}|\mathbf{x})}_{\text{NLL}} \geq \underbrace{\mathbb{E}_{q_\phi(\mathbf{z}|\mathbf{y},\mathbf{x})}[-\log p_\theta(\mathbf{y}|\mathbf{x},\mathbf{z})]}_{\text{negative reconstruction error}} + \underbrace{\mathbb{D}_{\text{KL}}(q_\phi||p_\theta)}_{\text{posterior-prior gap}}[\mathbf{x}]$$

- ◆ **Posterior collapse:** Posterior distribution collapses to prior distribution ($\text{KL} \approx 0$)
- ◆ **Losing long-term dependence:** AR generation ignores \mathbf{z} in the long term

Latent-Variable Model



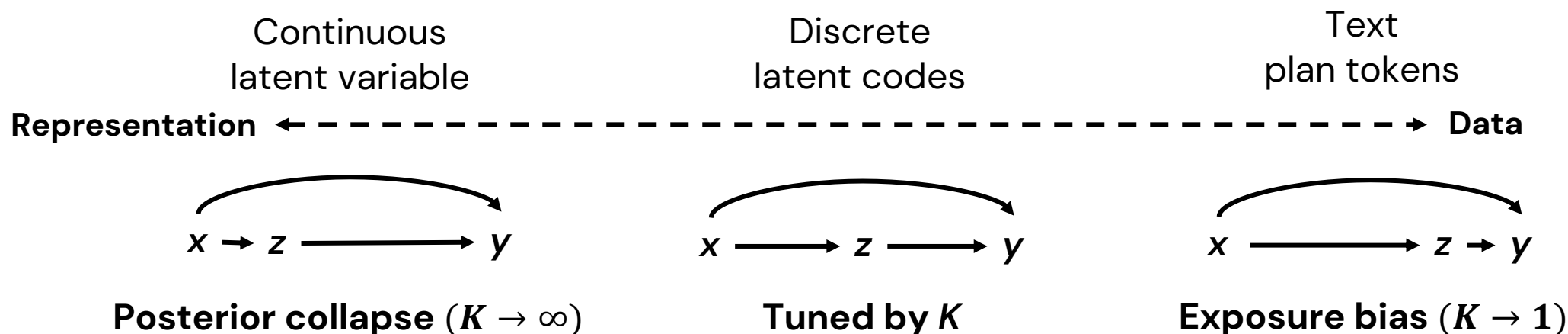
- AR model with structural discrete latent codes [Ji et al., 2021] (*EMNLP' 21 Oral*):



- ◆ Discrete code sequence as “latent plan” that captures the long-term structure of y
- ◆ **Controlled latent capacity:** # latent codes (L) \times # code vocabulary (K)
- ◆ **Decoupling ELBO learning** (due to discretization):
 - Obtain code by argmax over posterior distribution
 - Prior AR model learn the code by MLE

Takeaway & Future :

- ◆ A good latent representation control **amortization** of the “bottleneck”



- ◆ Hierarchical latent-variable model: diffusion model
 - Amortize sampling into multiple stages
 - Diffusion for AR LM



- ◎ **Beyond MLE:** Quality-aware objective

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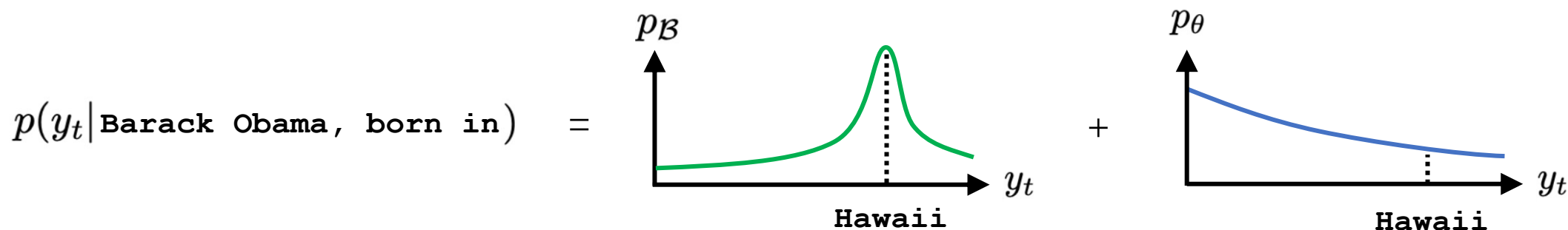
- ◆ Energy-based model [ICLR' 24]: Augment AR model with a residual energy model
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Look-Up Model



- ◉ **Advantage:** Retrieve low-frequency “items” from the distribution long tail
- ◉ **Disadvantage:** Naïve look-up model has exploding parameters that stores “all” sequences.
- ◉ **Practical look-up model:** Semi-parametric models
 - ◆ \mathcal{B} : Database, e.g., text documents, knowledge graphs, etc.
 - ◆ θ : AR parameters

$$p(y_t | \mathbf{x}, \mathbf{y}_{<t}) = \lambda(\mathbf{x}, \mathbf{y}_{<t}) \underbrace{p_{\mathcal{B}}(y_t | \mathbf{x}, \mathbf{y}_{<t})}_{\text{Database look-up}} + [1 - \lambda(\mathbf{x}, \mathbf{y}_{<t})] \underbrace{p_{\theta}(y_t | \mathbf{x}, \mathbf{y}_{<t})}_{\text{AR prediction}}$$



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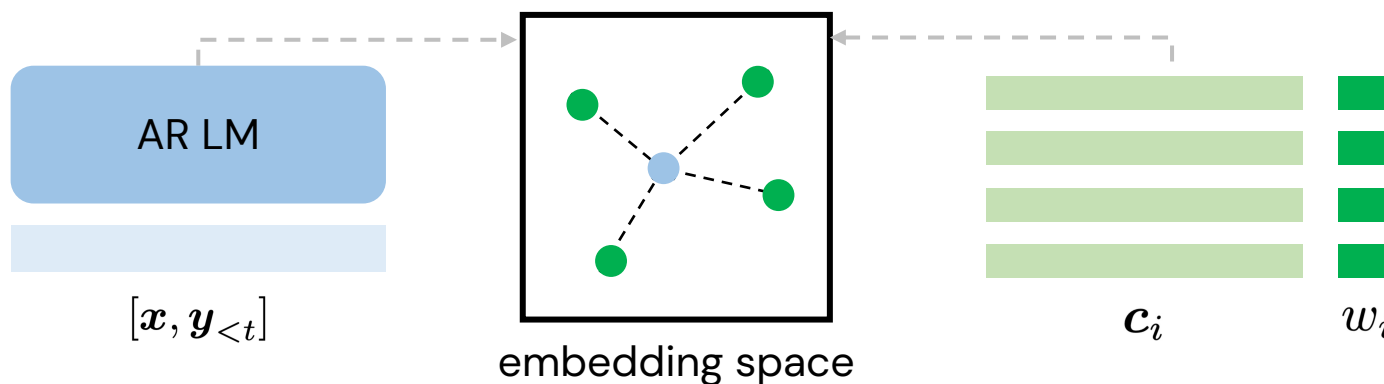
- ◉ **Parametric vs Non-parametric:**
 - ◆ Parametric AR model is effective at learning local text continuity
 - ◆ Non-parametric database is efficient in capturing sparse relationship

Look-Up Model



- Semi-parametric model with text-based \mathcal{B} (kNN-LM) [Khandelwal et al., 2020]:

- ◆ **key-value** from text documents \mathcal{D} : $\mathcal{B} = \{(c^i, w^i) \mid [c^i, w^i] \in \mathcal{D}\}$



$$p_{\mathcal{B}}(y_t \mid \mathbf{y}_{<t}, \mathbf{x}) \propto \sum_{(c^i, w^i)} \mathbb{1}[y_t = w^i] \exp(\text{sim}(c^i, [\mathbf{x}, \mathbf{y}_{<t}]))$$

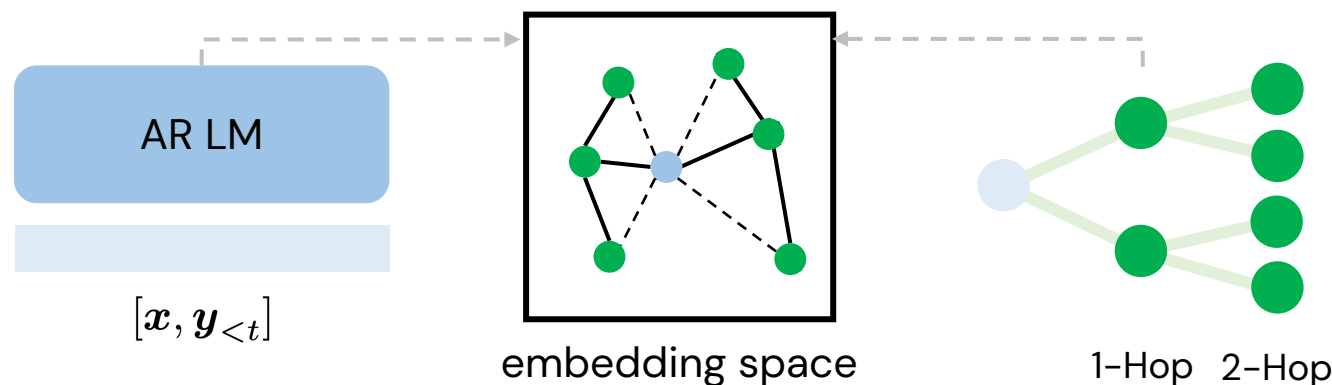
- ◆ Soft matching by context similarity (legacy of text representation learning)
- ◆ The complexity of database grows linearly with the size of training data!

Look-Up Model



⊙ Semi-parametric model with graph-based \mathcal{B} [Ji et al., 2020] (*EMNLP' 20 Oral*):

◆ **Trie** from knowledge graph $\mathcal{G} = (\mathcal{E}, \mathcal{R})$: $\mathcal{B} = \{\tau^i = (\dots, e_j^i, r_{j,j+1}^i, e_{j+1}^i, \dots) \mid e_j^i, e_{j+1}^i \in \mathcal{E}, r_{j,j+1}^i \in \mathcal{R}\}$



$$p_{\mathcal{B}}(y_t | \mathbf{y}_{<t}, \mathbf{x}) \propto \exp \left(\sum_{\tau^i} \sum_{j=1}^H \mathbb{1}[y_t = \tau_j^i] \text{sim}(\tau_{<j}^i, [\mathbf{x}, \mathbf{y}_{<t}]) \right)$$

◆ **Gain of structure:**

- Accumulate and reuse evidence along the branch of the tree
- The complexity of tree grows linearly with the context length ($\ll \# \text{docs}$)

◆ Build graph from documents to increase connectivity (followed by future works)

Look-Up Model



⦿ Takeaway & Future :

⦿ Look-up at decoding phase:

- ◆ Semi-parametric model: Merging look-up probability with LM probability
- ◆ Induce noise, need dynamic balancing the intensity

⦿ Look-up at encoding phase:

- ◆ Retrieve-Augmented Generation (RAG): LM performing implicit look-up
- ◆ High fluency with hallucination

Conclusion & Future



○ Push the boundary of language modeling in a **principled** and **scalable** way:

○ **#1** Learn from Data in high quality

◆ Fine-grained annotations:

Generative → **Preferential** → **Process** → ?

◆ **Solution:** Quality-aware objective

• **Key:** quality evaluation

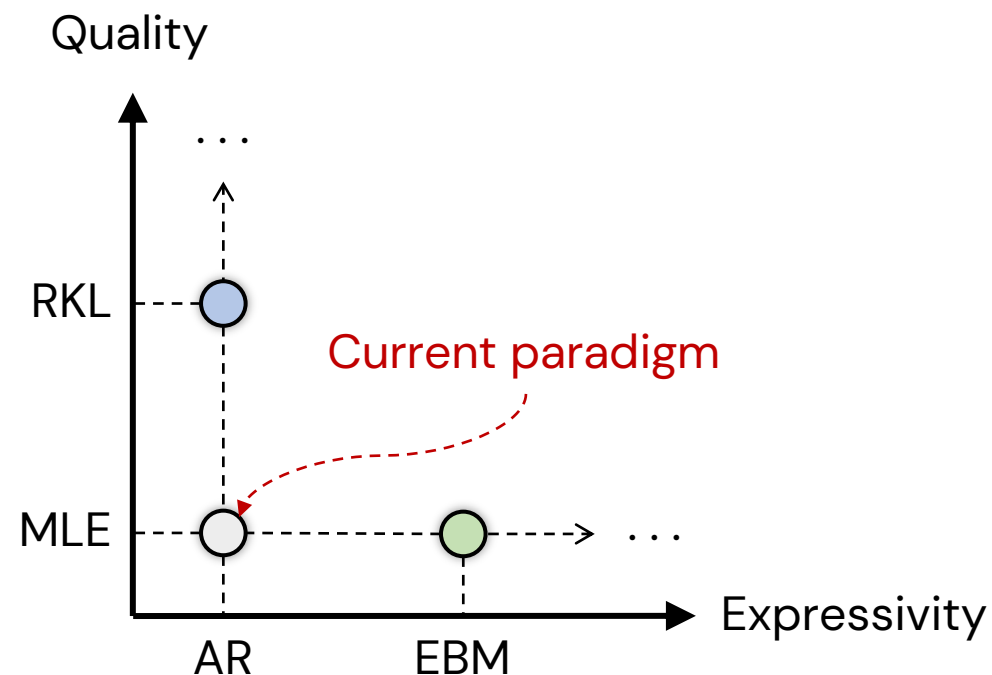
○ **#2** Increase model expressivity

◆ Data growing slows down

• Need to increase data utilization

◆ **Solution:** Expressive model families

• **Key:** Scaling up upon AR model



Thanks for Attention!



Q & A

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